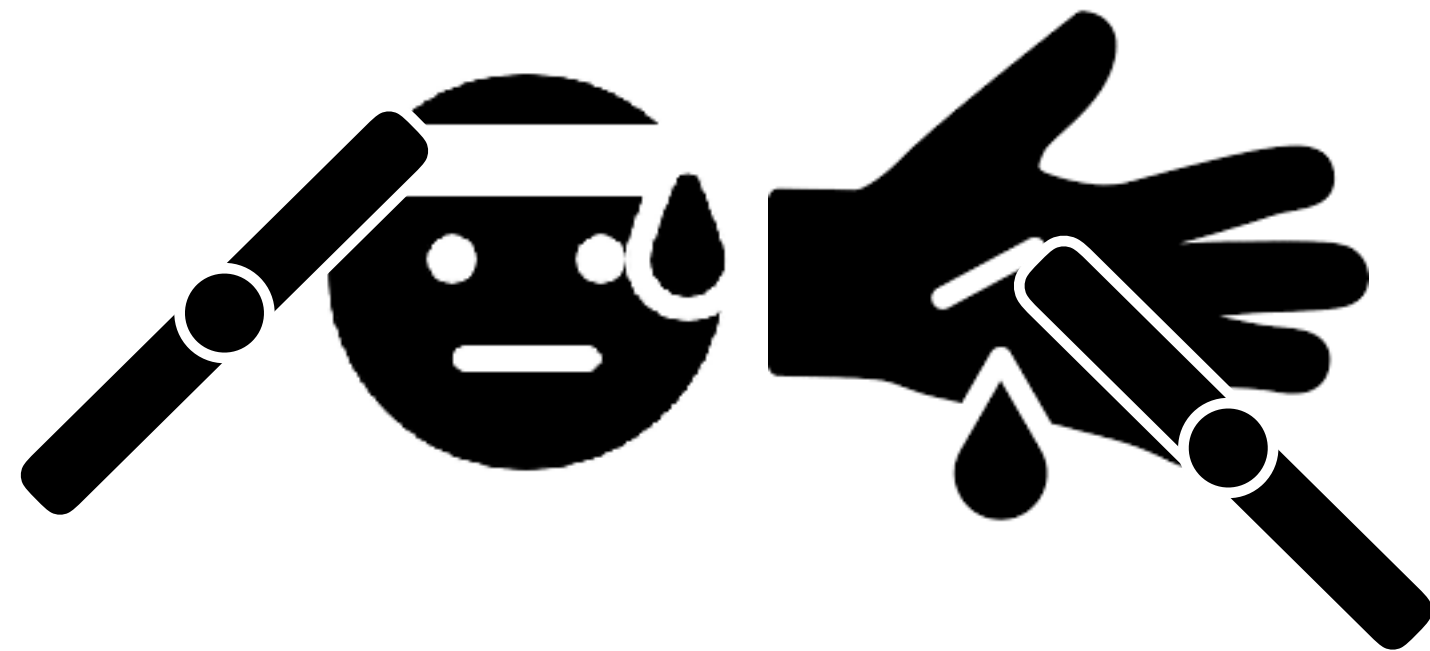


# Safety warning

**Fast rotation propellers can hurt humans and animals**

**To prevent injury, do:**

- Keep hands off a running vehicle
- If you loose control of the vehicle, stop immediately



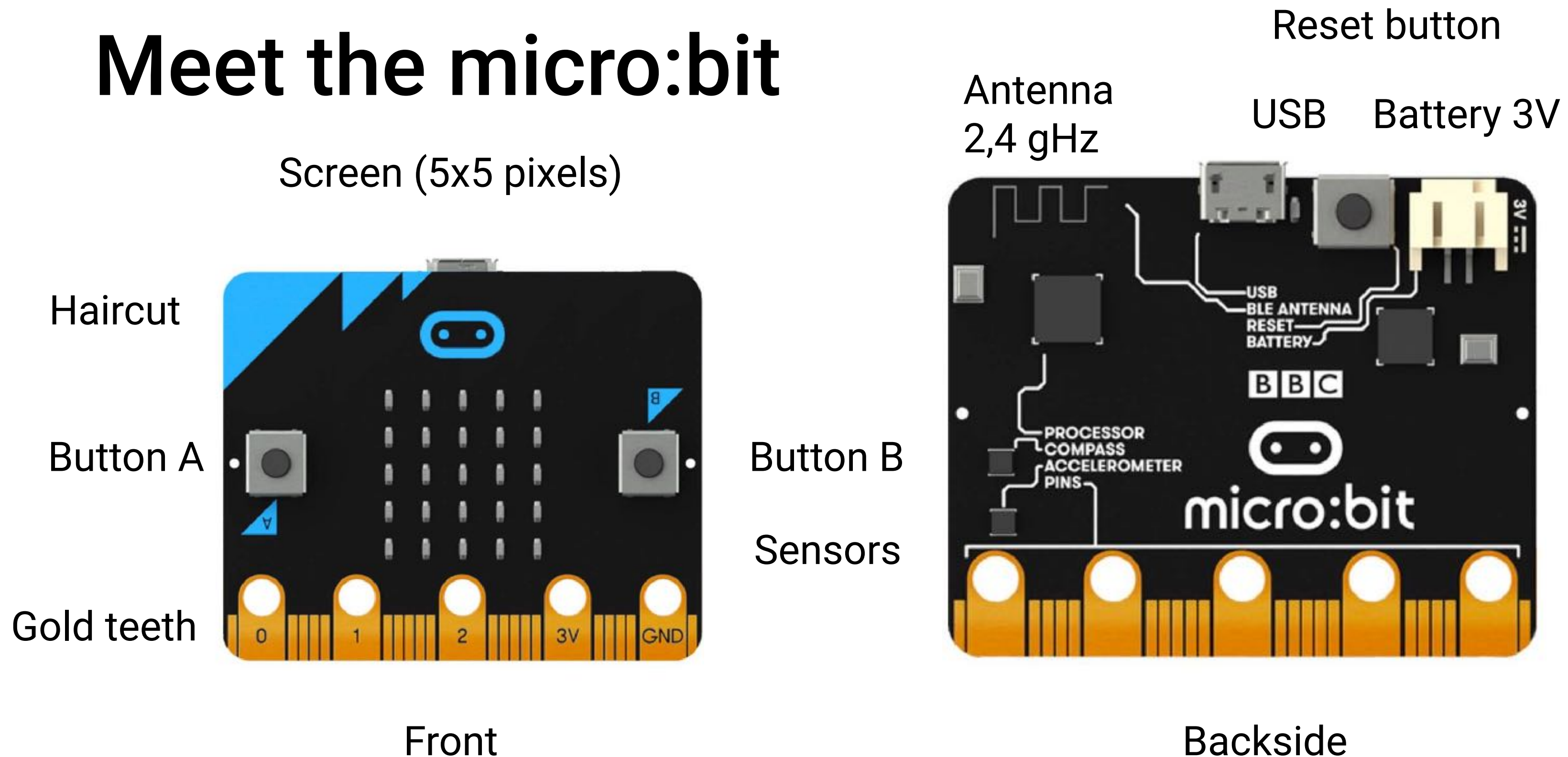
**Lithium batteries can release smoke or cause a fire**

**To prevent damage, do:**

- Don't charge the batteries unattended
- Don't use a damaged or punctured battery
- Do not short circuit the battery
- Avoid temperatures below -10 and above 50 degrees celcius.
- Don't use batteries that are colder than 15 degrees celcius
- Always have a plan for what to do in case of a fire: If you are indoor, open a window and get the battery outside to prevent smoke or fire.
- Do not open or modify the battery in any way.
- For optimal performance, store the battery at around 30% capacity and between 10 and 20 degrees celcius
- Follow airport regulations for carrying lithium batteries on airplanes. (Usually hand luggage only)



# Meet the micro:bit

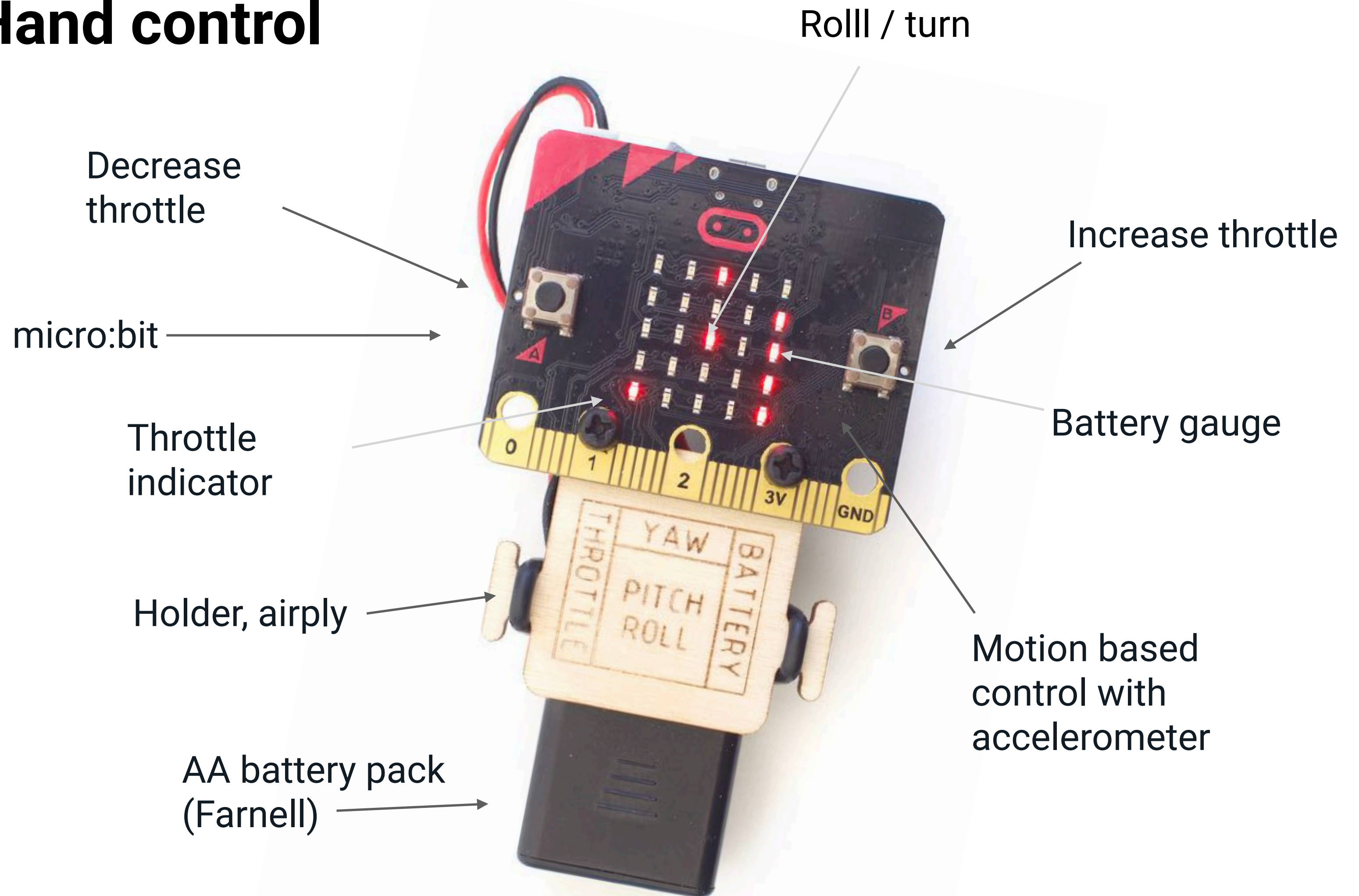


micro:bit is a small computer with prosessor, sensors, display and radio. It has connection pins for external components like LEDs, speakers or various sensors.

You can learn more at: <https://tech.microbit.org/hardware/>



# Hand control



# Control board

By MakeKit and SPRacing

Charge port +  
firmware update  
(micro USB)

Main switch

Battery plug

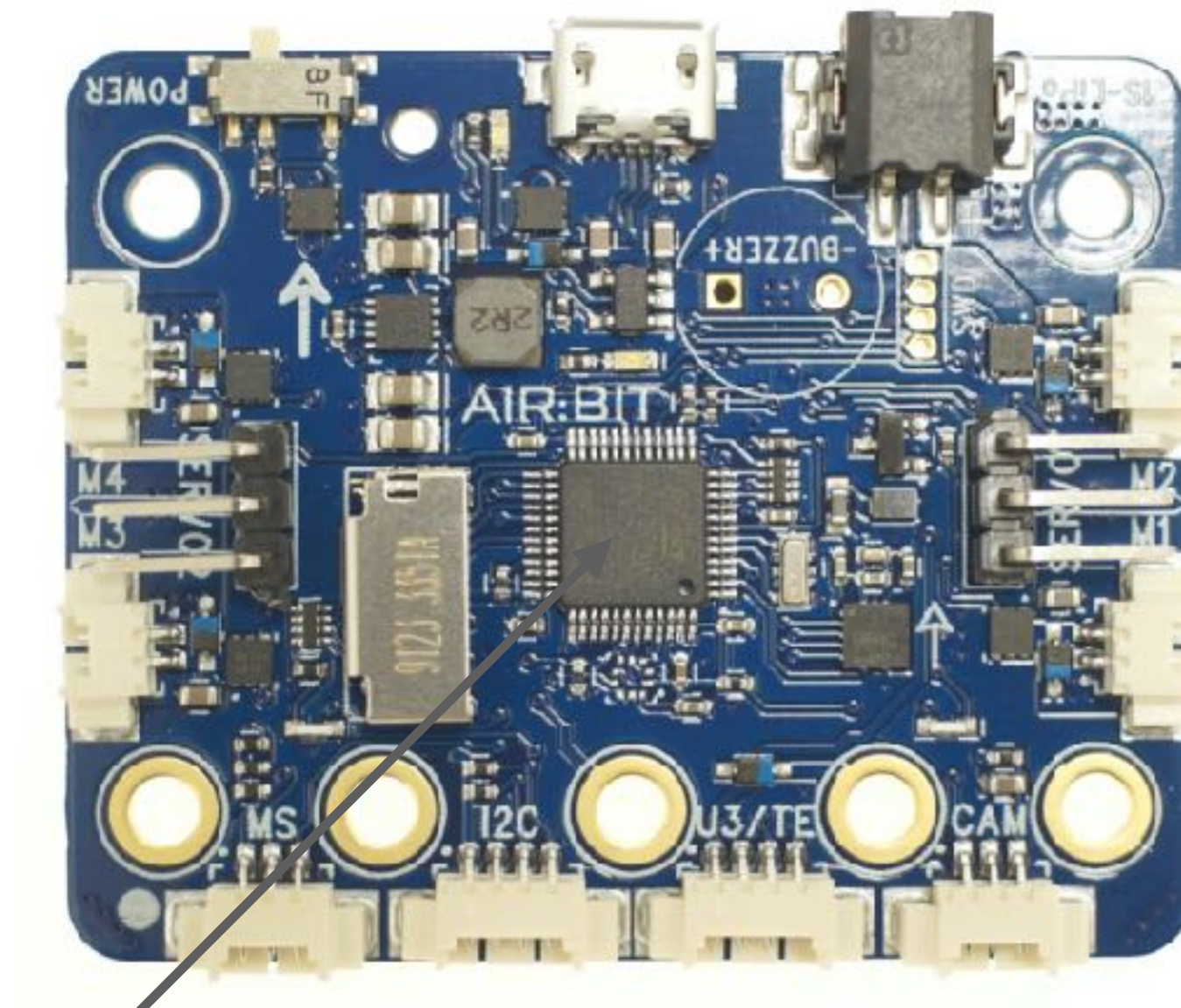
Off On

Servo connector

Motor 1 (push)

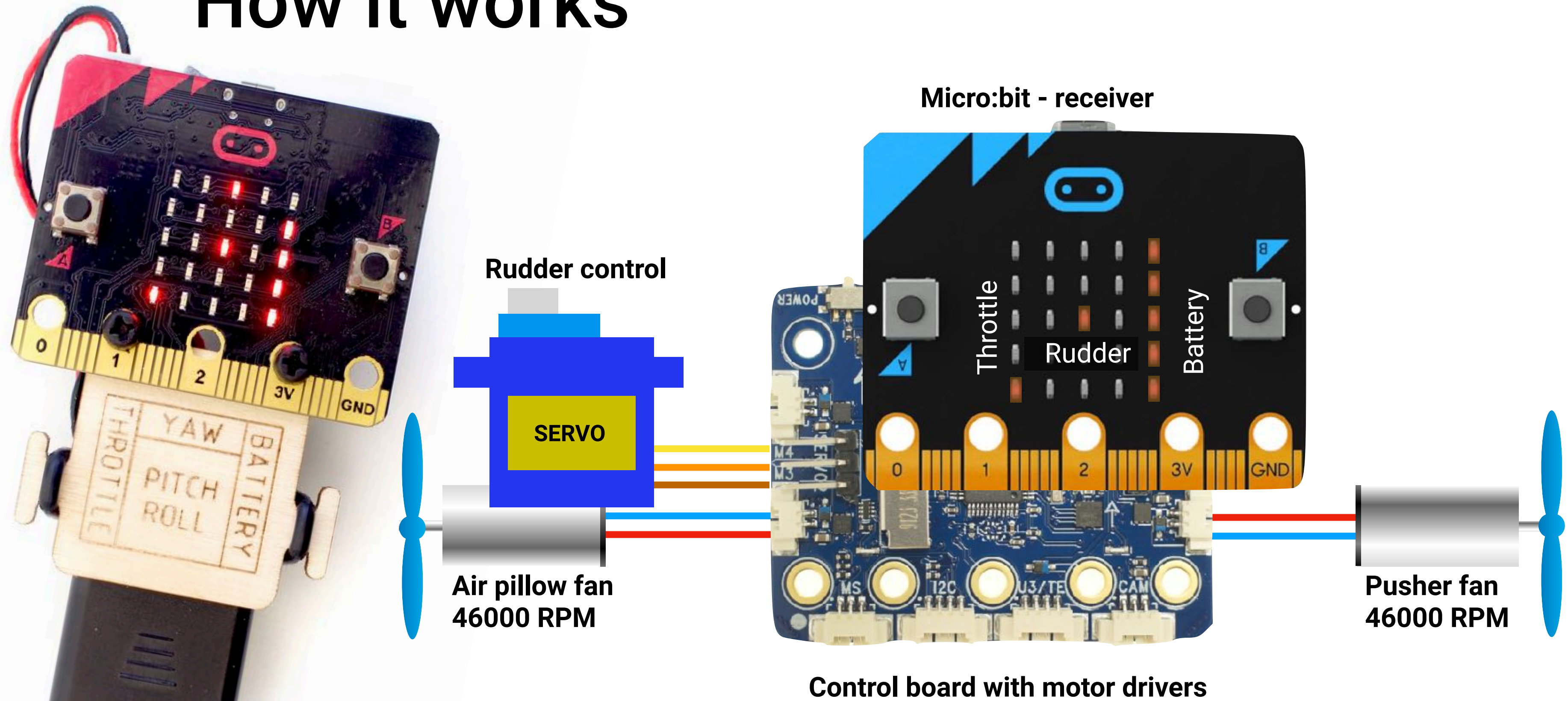
Motor 2 (skirt)

STM32 F303 processor  
With Betaflight software





# How it works





# Charging

## Parts:

Off / On Battery



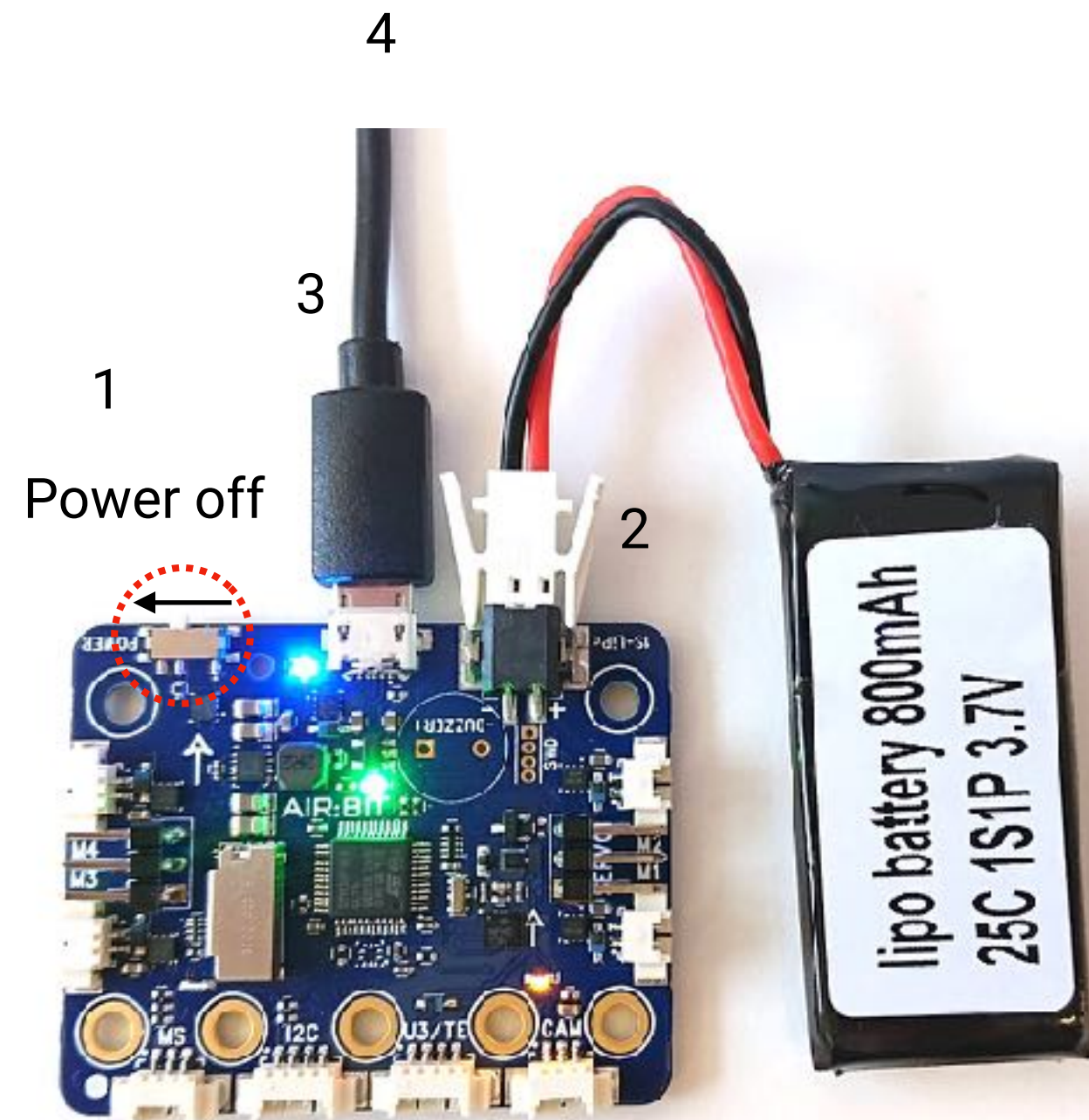
Air:bit control board



Lithium (LiPo)-  
battery



Micro USB-  
Cable



- The battery can be charge with or without the micro:bit mounted
1. Switch off the power
  2. Plug the big white plug into the grey connector "1s LiPo"
  3. Connect the micro USB into control board
  4. Connect the other end into a USB charge outlet
  5. Blue light indicates charging. When light goes off, charging is finished. (1-2 hours)

**Fire hazard:**  
**Never charge a Lithium battery unattended!**



# Tools

Must have:



Small  
philips  
screwdriver



Marker



Scissors



Utility knife



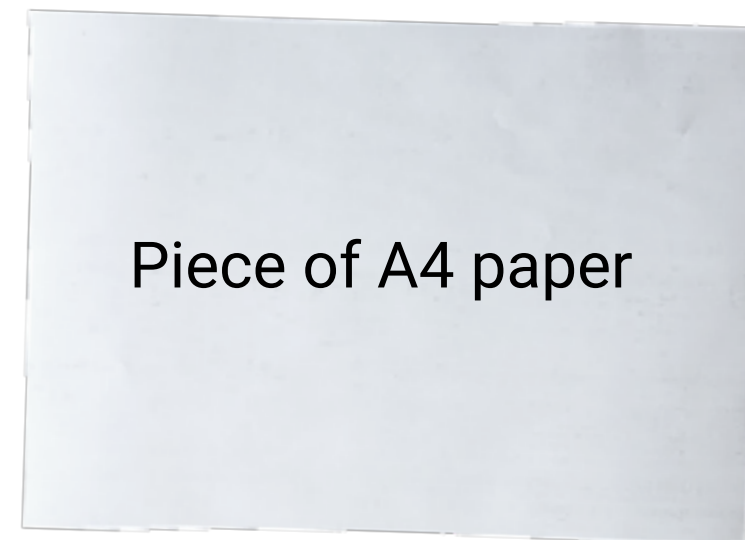
Ruler



Glue gun  
or  
contact  
adhesive glue



Recommended:



Piece of A4 paper



Socket wrench  
5.5mm

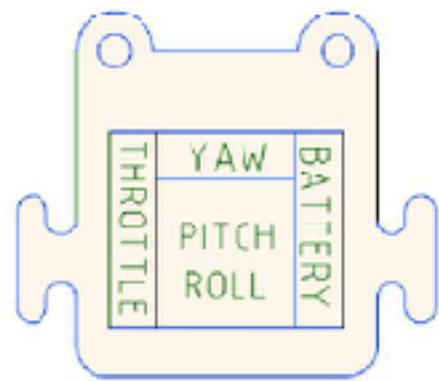


Small cutting pliers

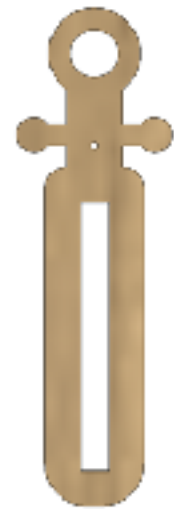
Nose pliers



# Parts



Remote holder



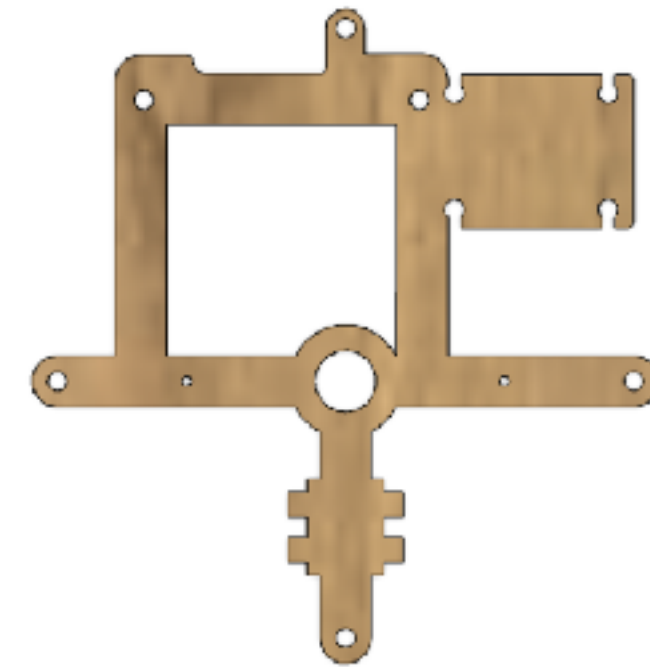
Tail fin holder



Motor holder



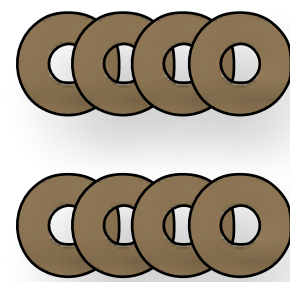
2x angle connectors



Base frame



Wedges



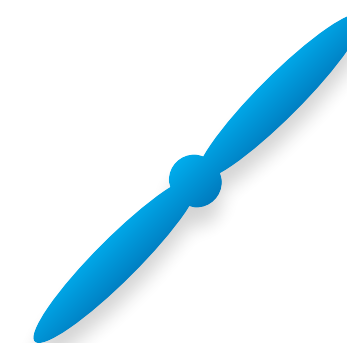
8x spacers



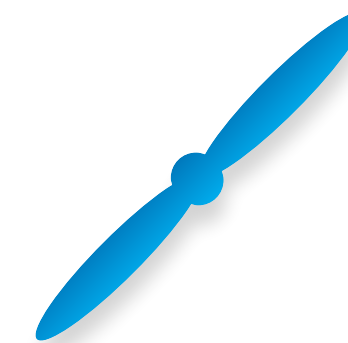
2x small O-rings



3 Large o-rings



1 CW propeller



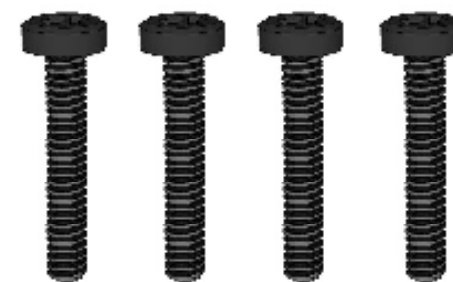
1 CCW propeller



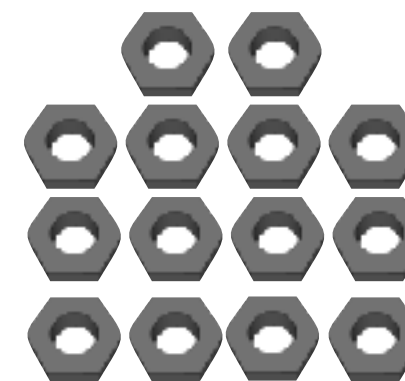
2x m3x8 nylon screws



4x m3x12 nylon screws



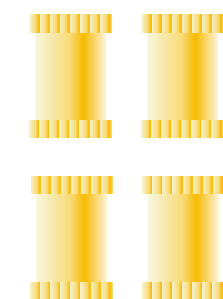
4x m3x15 nylon screws



14x nylon nuts



2x m3x12 countersunk



4 stk knurled barrel nuts



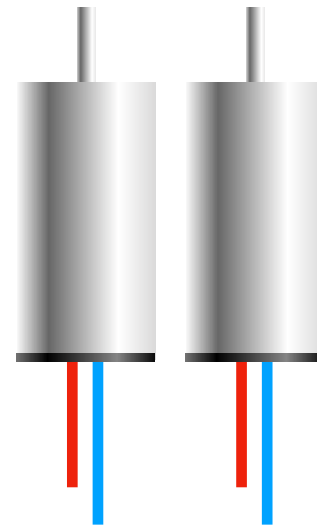
# Parts (electronics)



Servo motor



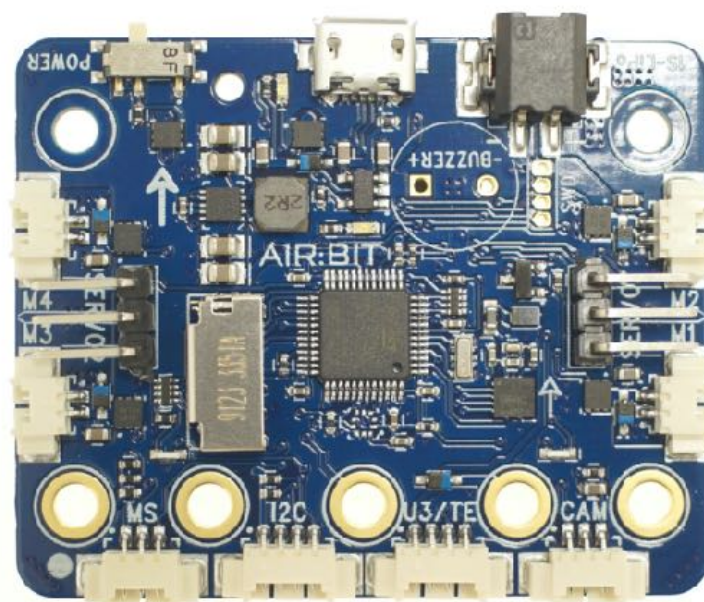
Servo horn



2x Motors



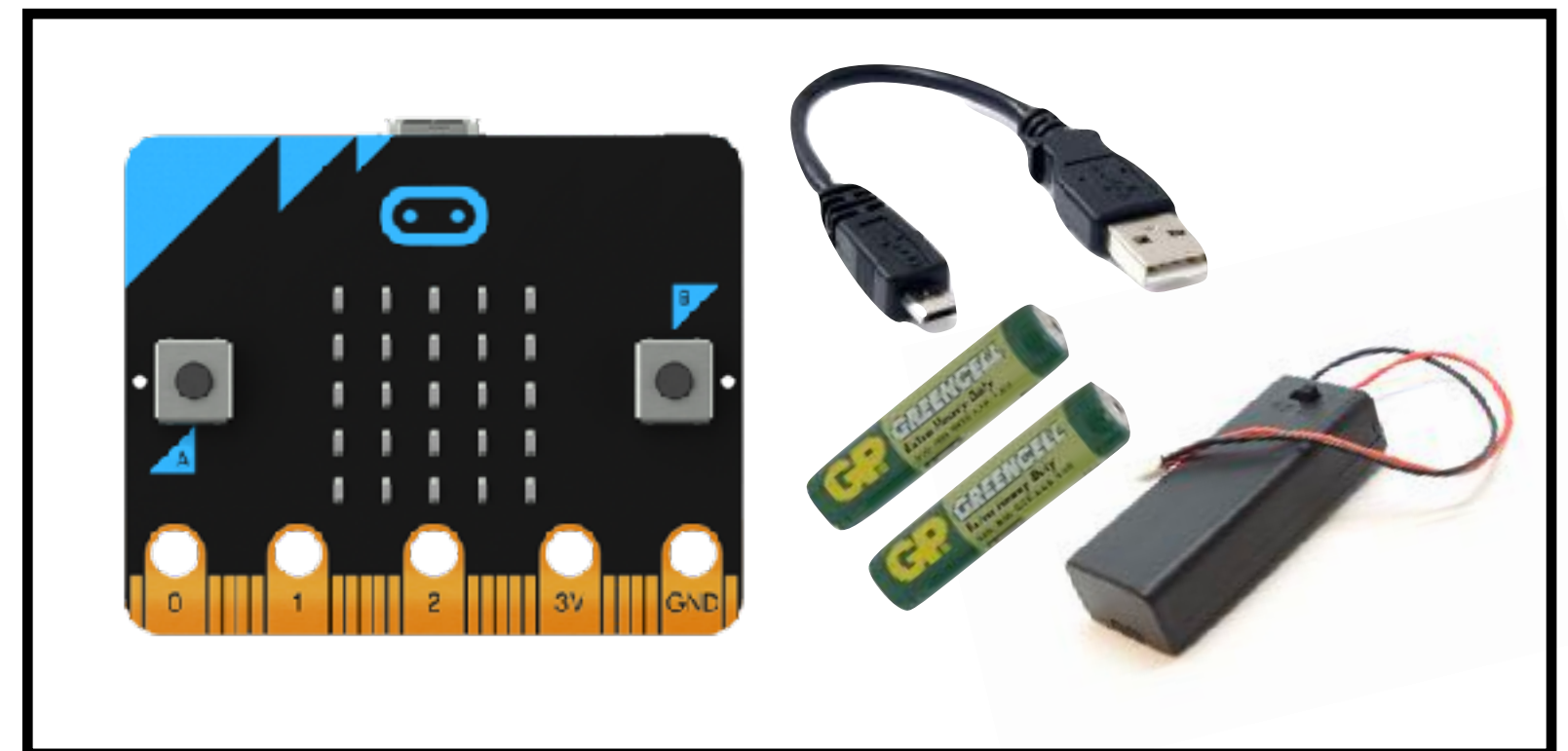
Ziplock bag, 15x20 cm



Control board



Lithium battery



1-2 Micro:bit start kit (sold separately)

# Assembly



# Assemble the remote (skip if you made the Air:bit)

Tools: Philips Screwdriver

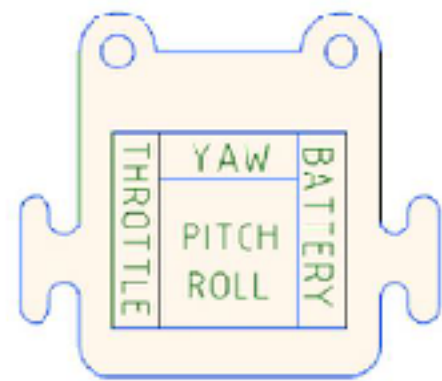
## Parts:



2 nylon screw  
m3x8



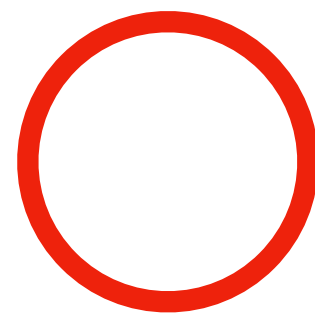
2 nylon  
nuts m3



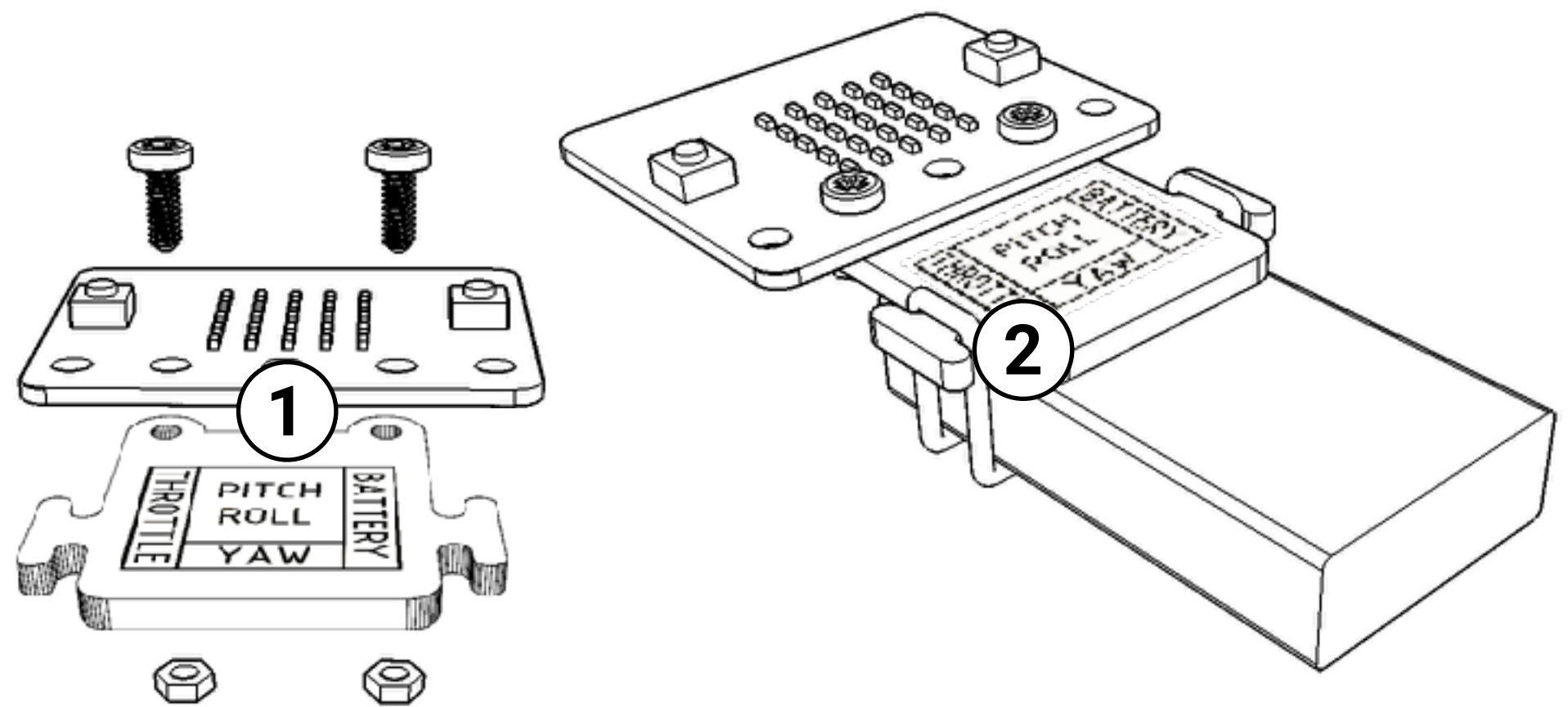
Remote holder



Battery box AAA



Large silicone ring



- Place the micro:bit with **screen facing up** on top of the holder (1)
- Make sure the remote holder also is **facing up**
- Mount battery box with the silicone ring (2)

# Control board (skip if you made the Air:bit)

**Tools:** Philips Screwdriver

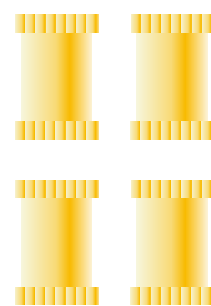
**Deler:**



4 stk nylon screws m3x12



Airbit control board



4 knurled  
barrel nuts



- Screw the barrel nuts to the control board. They will provide a connection to the micro:bit
- **Make sure they are "finger tight":**
  - Tight enough to provide a steady connection
  - Not so tight the screw is damaged



# Countersunk screws (skip if you made the Air:bit)

**Tools:** Philips Screwdriver

## Parts:



2 x  
countersunk  
screws



2 x  
Nylon nuts



Assembled control board



- Pull the screws trough and attach the nuts on the bottom side of the board

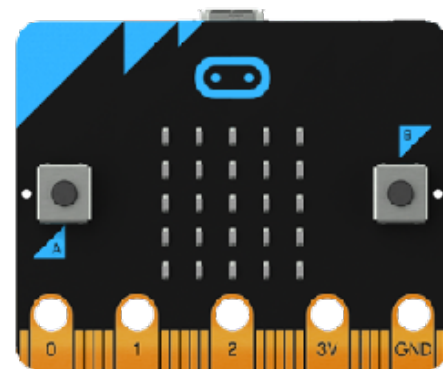
# micro:bit (skip if you made the Air:bit)

**Tools:** Philips Screwdriver, pipe wrench 5.5mm

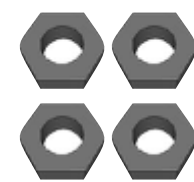
**Deliver:**



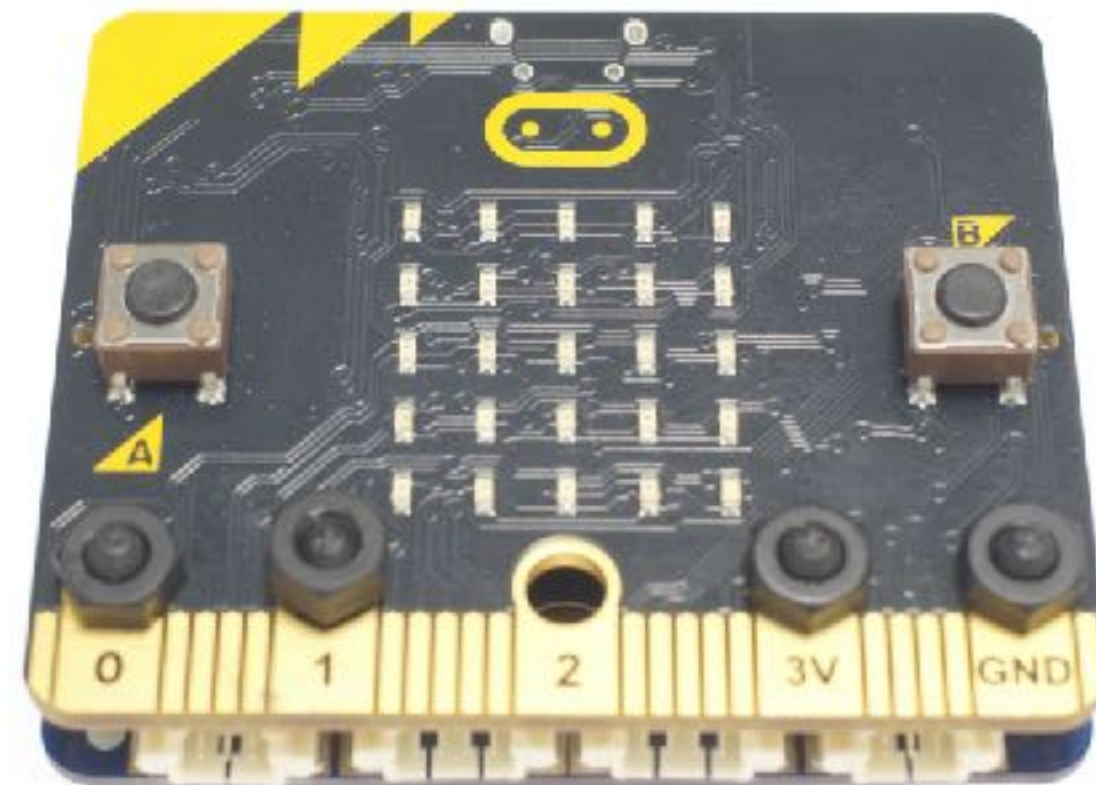
Assembled control board



micro:bit



4 nuts



- Place the micro:bit on the barrel nut on the control board
- Screw on the nuts “finger tight” so the connection is solid but you don’t damage the plastic screws.



# Making the raft

**Tools:**  
Utility knife or scissors

**Parts:**



Cardboard box from kit



- Carefully cut along the dotted lines
- Cut out one of the tail fins





# Making the raft

Tools:  
Marker

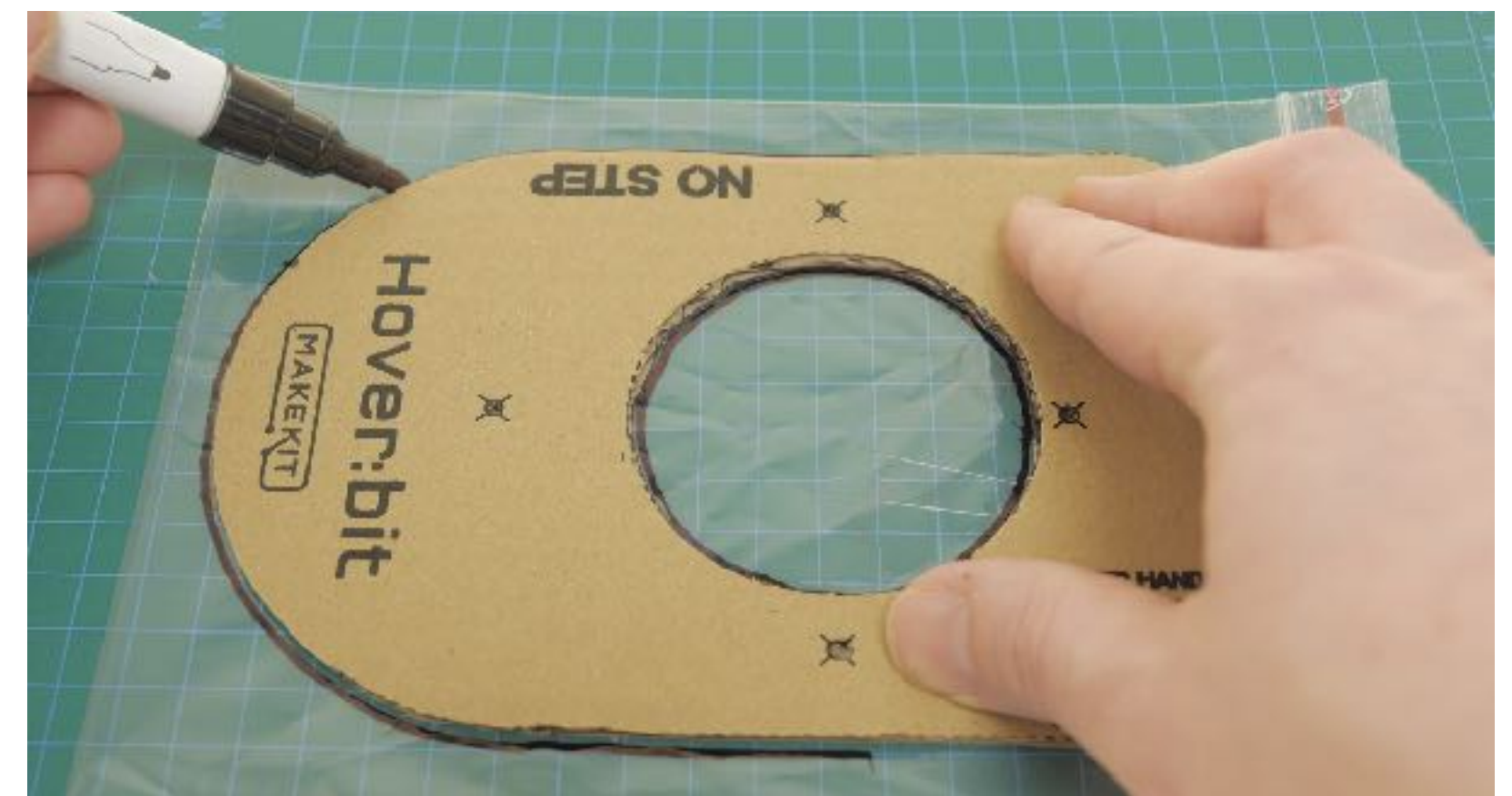
Parts:



Cardboard parts



Large ziplock bag from kit



- Place cardboard exactly in the middle of the ziplock bag
- Mark the inner circle and the outer line with a marker



# Making the raft

Tools:  
Marker

Parts:



Cardboard raft



4 nylon screw  
m3x15

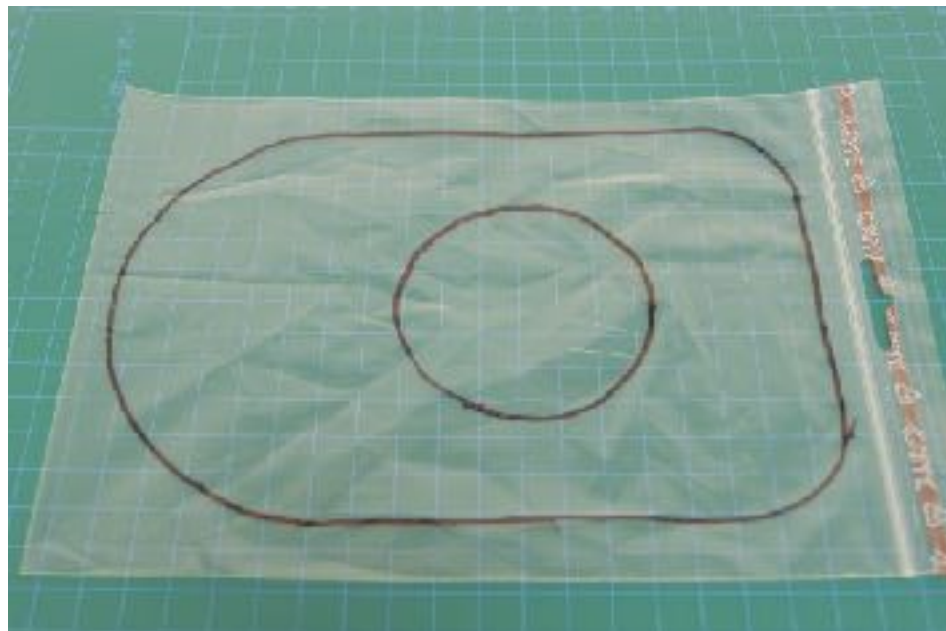


- With a small screwdriver or sharp tip, punch 4 thin holes in the marked crosses.
- Insert the four screws as shown above

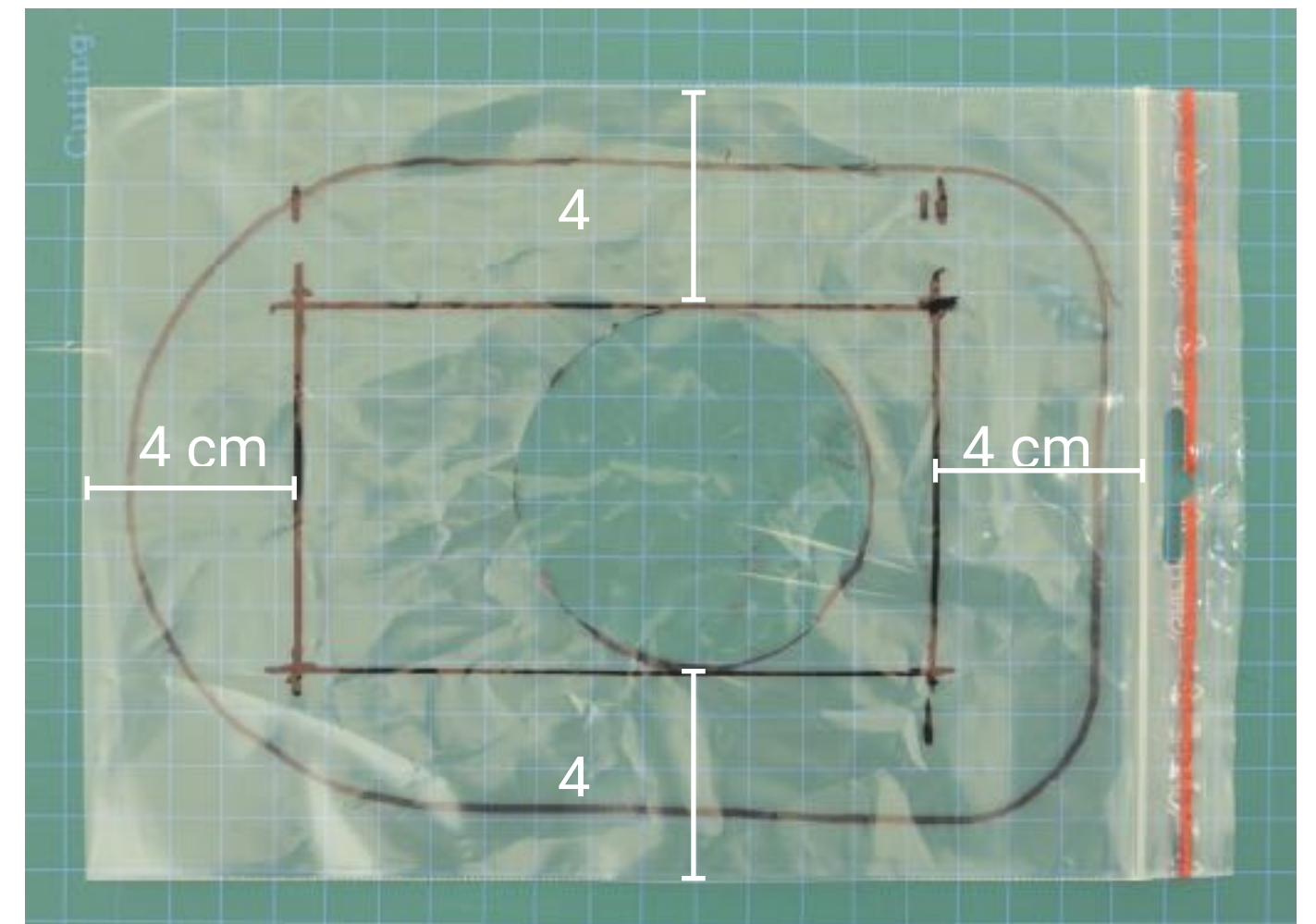
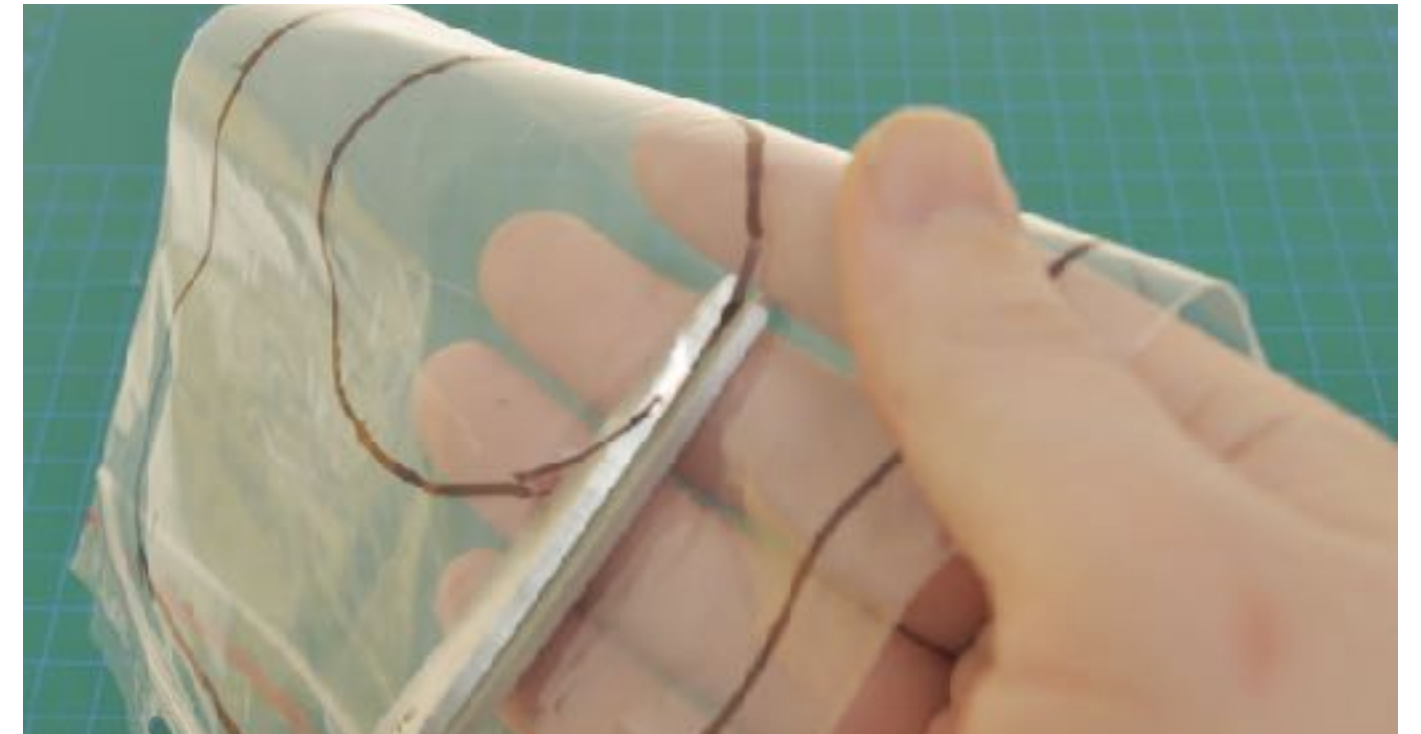
# Making the raft

**Tools:**  
Scissors  
Marker

**Parts:**



Ziplock bag



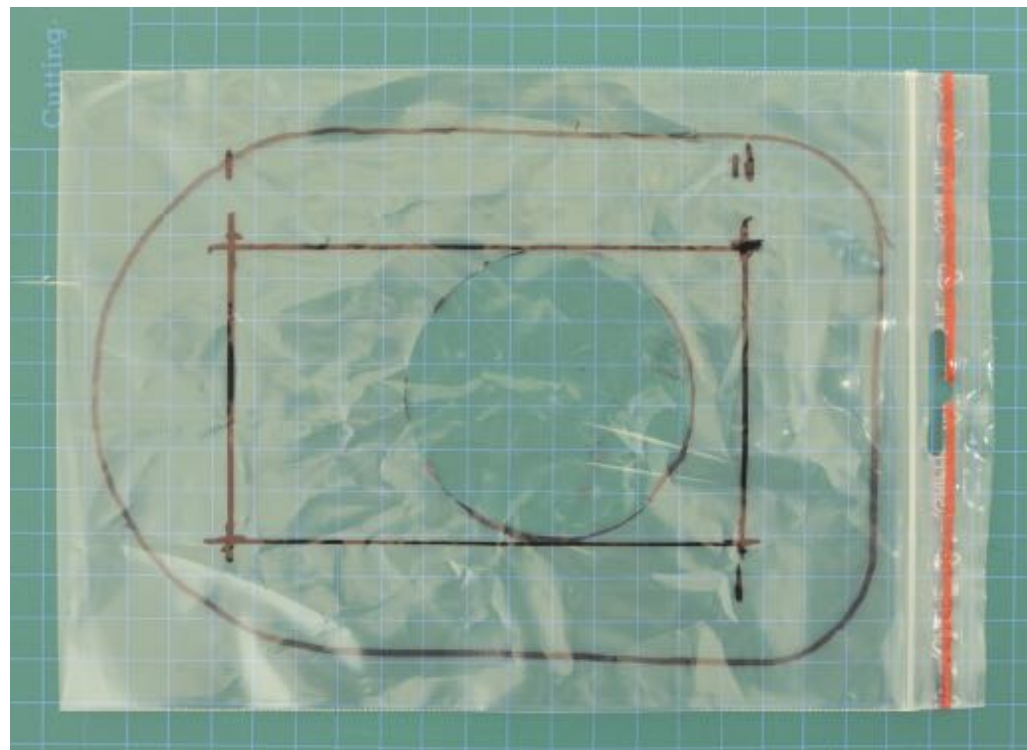
- On **one side** of the ziplock bag, cut out the marked hole with a pair of scissors
- On the **other side** of the bag, use a ruler to draw a square 4 cm from the edges.



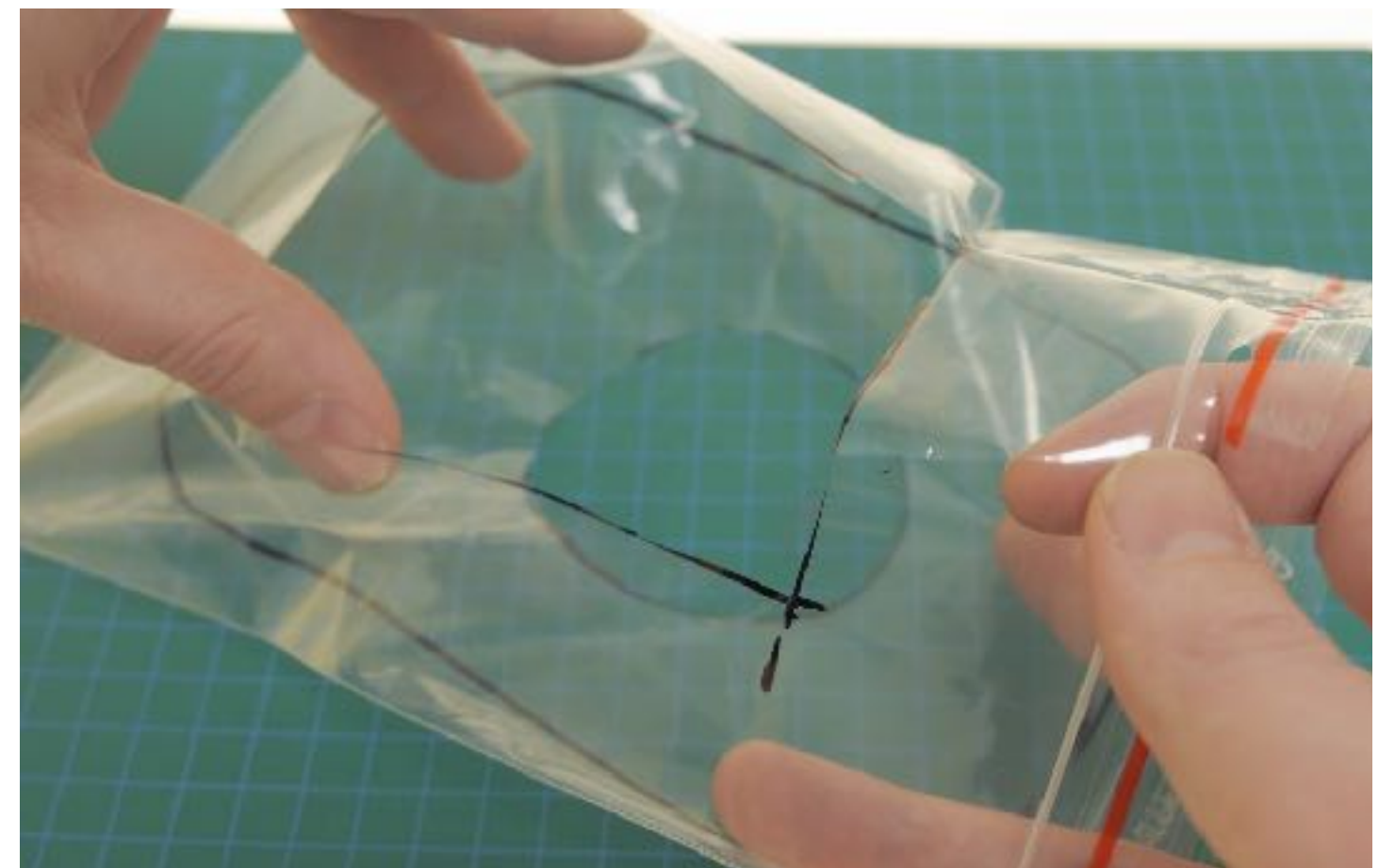
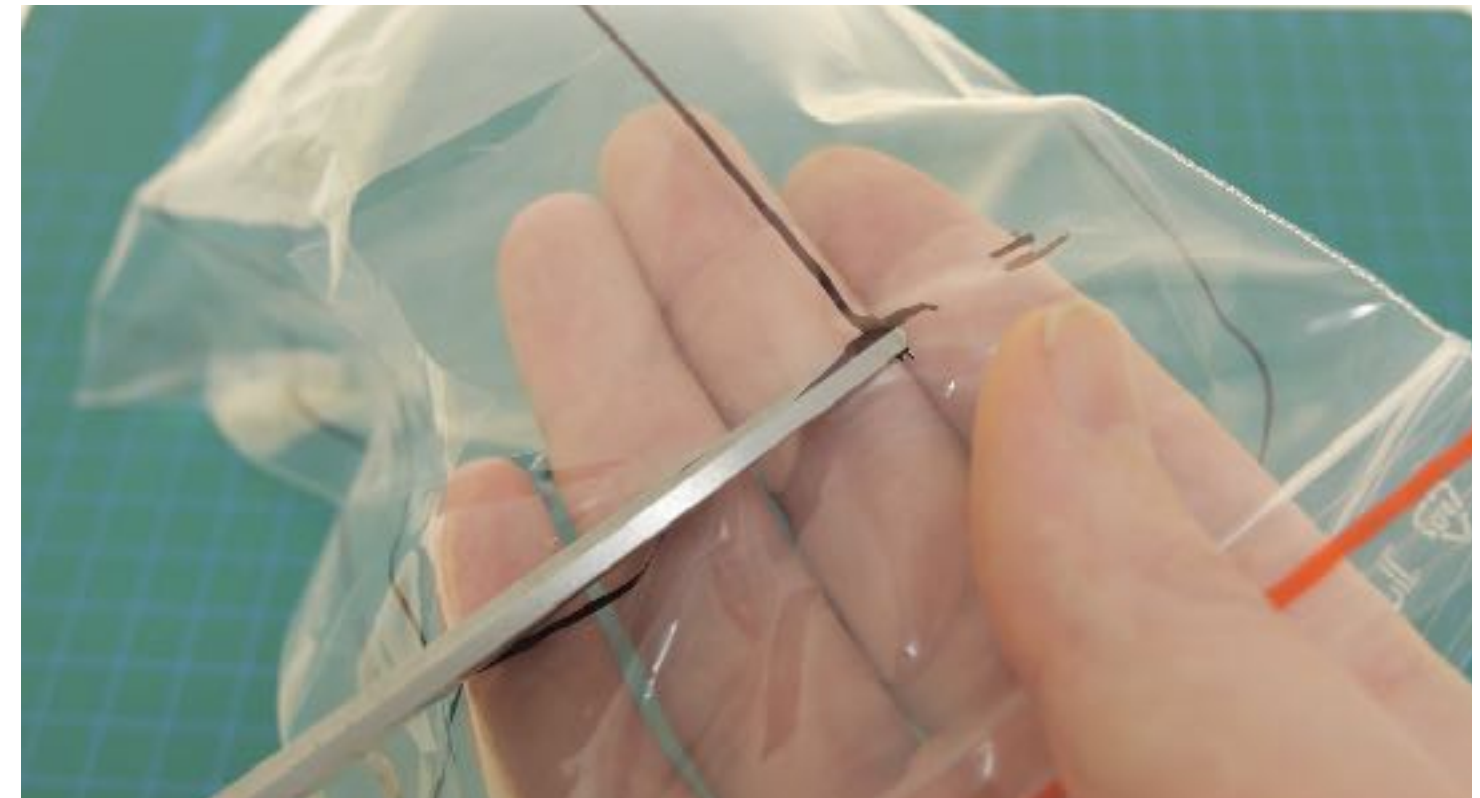
# Making the raft

**Tools:**  
Scissors

**Parts:**



Ziplock bag



- Carefully cut out the square on back side only
- The bag should have a square hole on one side and a hole on the other side.

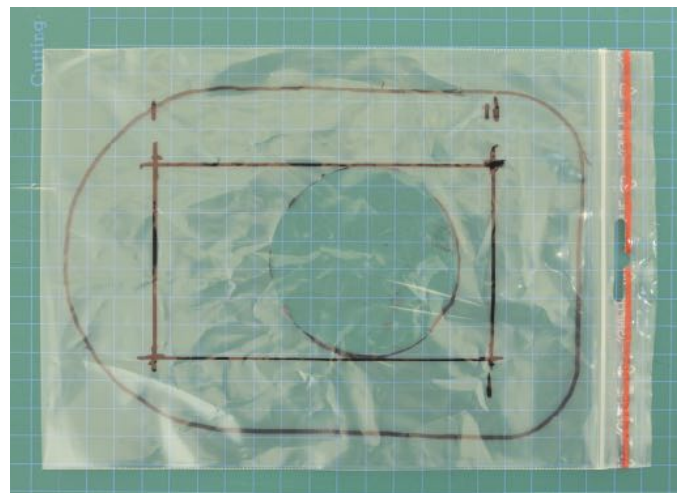


# Making the raft

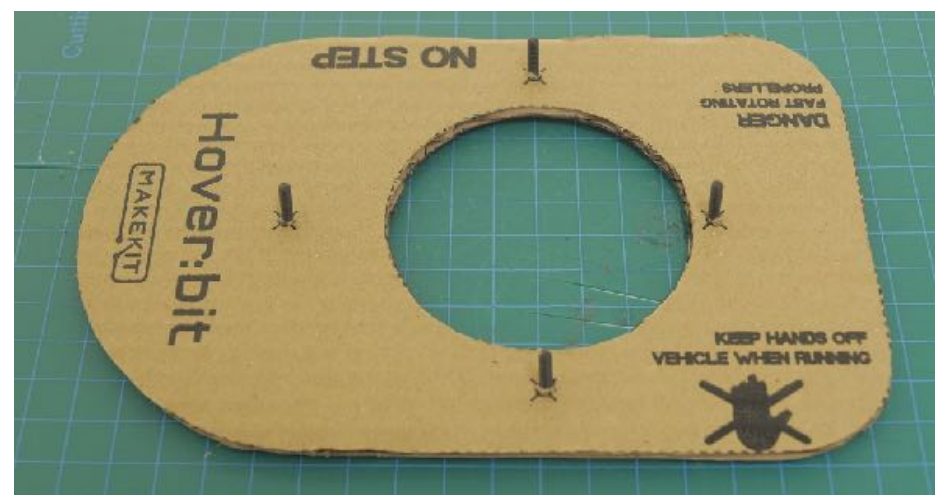
## Tools:

Hot glue or contact adhesive glue

## Parts:



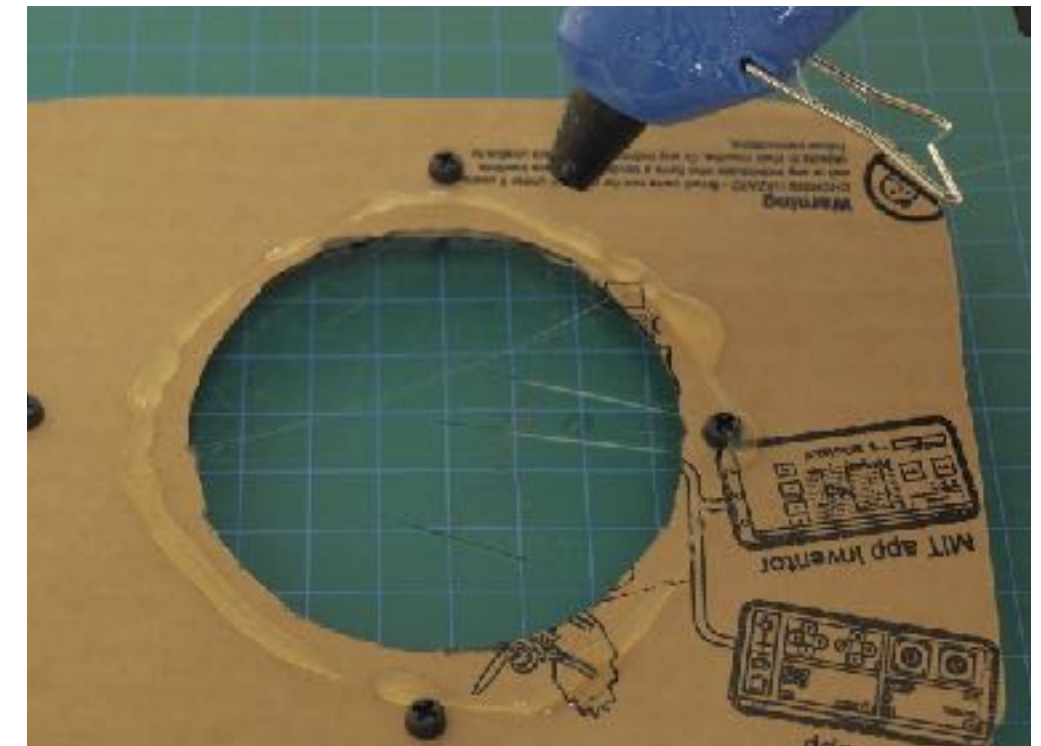
Ziplock bag



Raft with screws



- Turn the raft upside down.
- Place the bag so it matches the markings.
- Make sure the **big squared cutout is on top** and the circular hole is at the bottom.
- Remove the bag

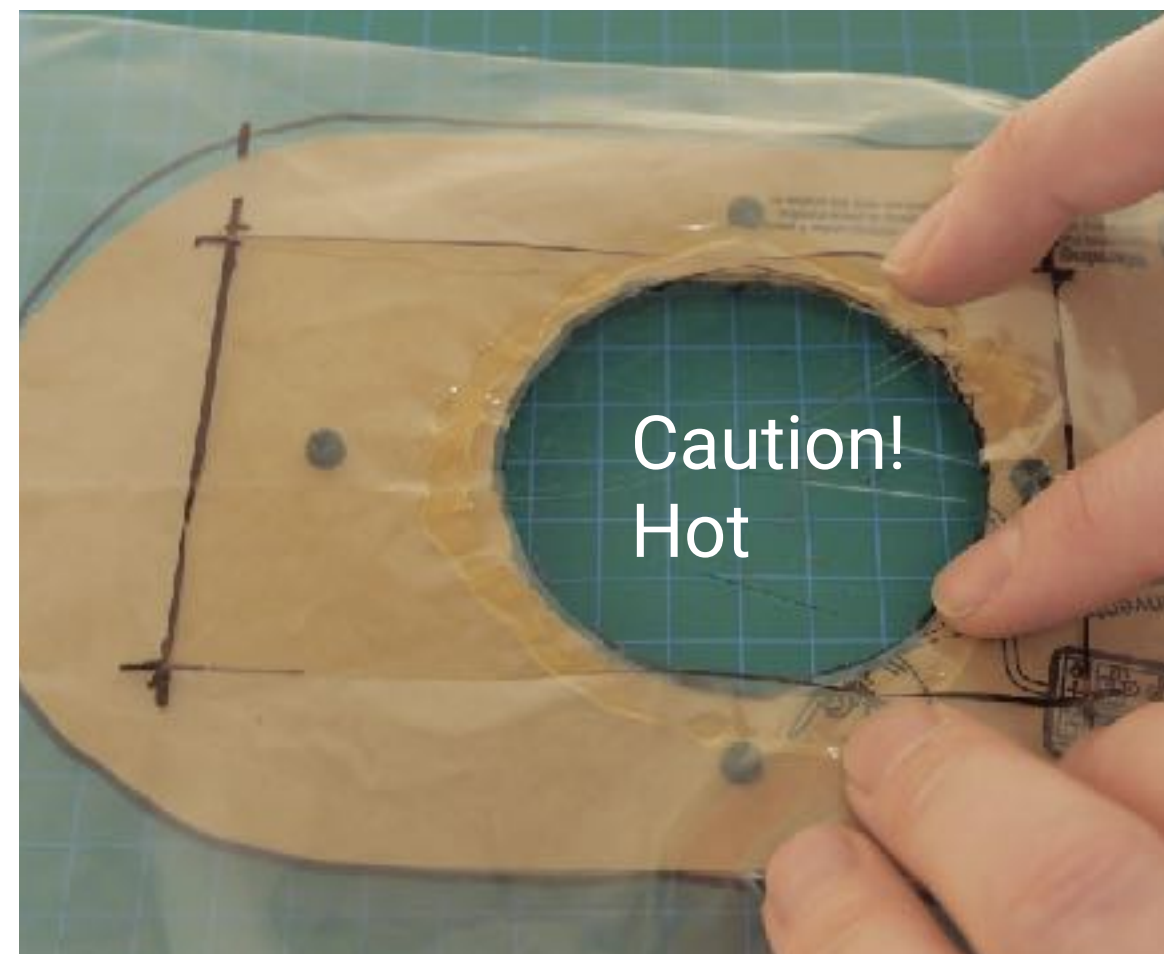


- Place hot glue around the hole

## You can also use contact glue



- Put a thin layer of glue around the hole
- Put a similar layer of glue around the hole on the bag
- Wait 2-5 minutes until the surfaces are dry
- Press together
- Other glues might not work on PE plastic bags



- Carefully place the bag so it aligns with the hole and the rest of the raft



# Making the raft

## Tools:

Hot glue or contact adhesive glue

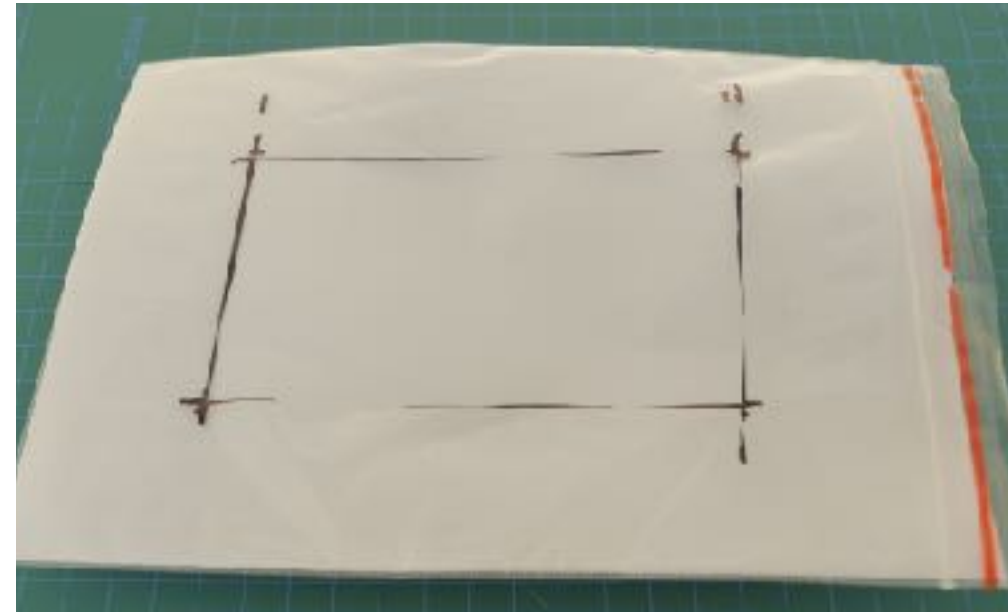
## Parts:



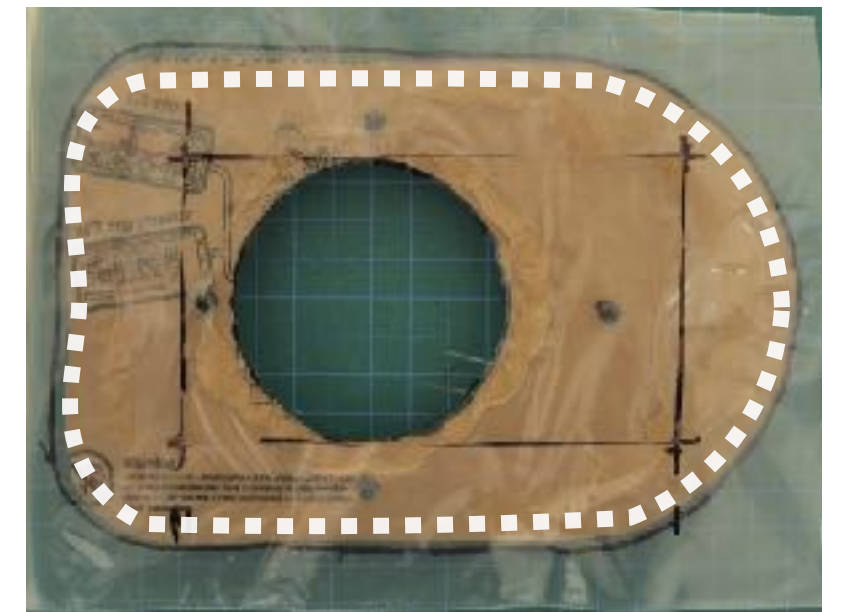
Glued raft



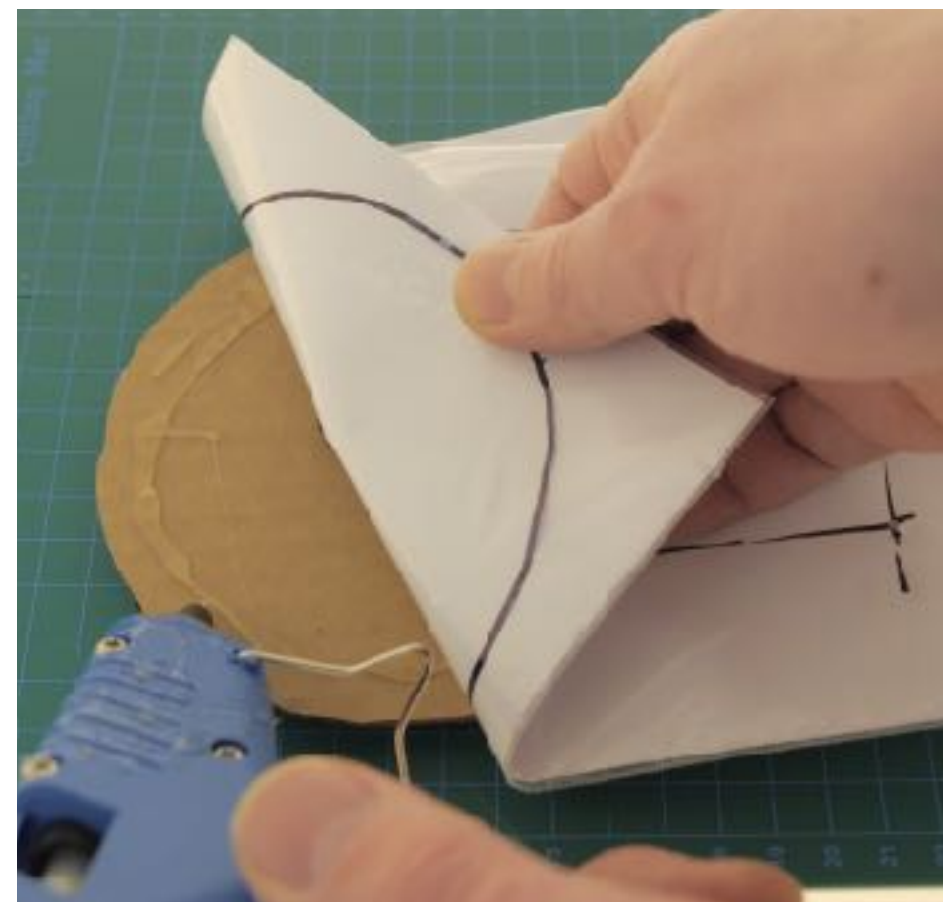
Piece of A4 paper



- To protect the bag from melting, fold a A4 paper and insert into the bag
- This is only needed if using hot glue



- Notice the “glue line” where the glue should be placed



- Start placing glue at the edges on one side of the raft
- Press the bag down to attach
- Move on to another part until the bag is glued all around the edge of the raft.
- If using contact adhesive, you can glue everything at the same time



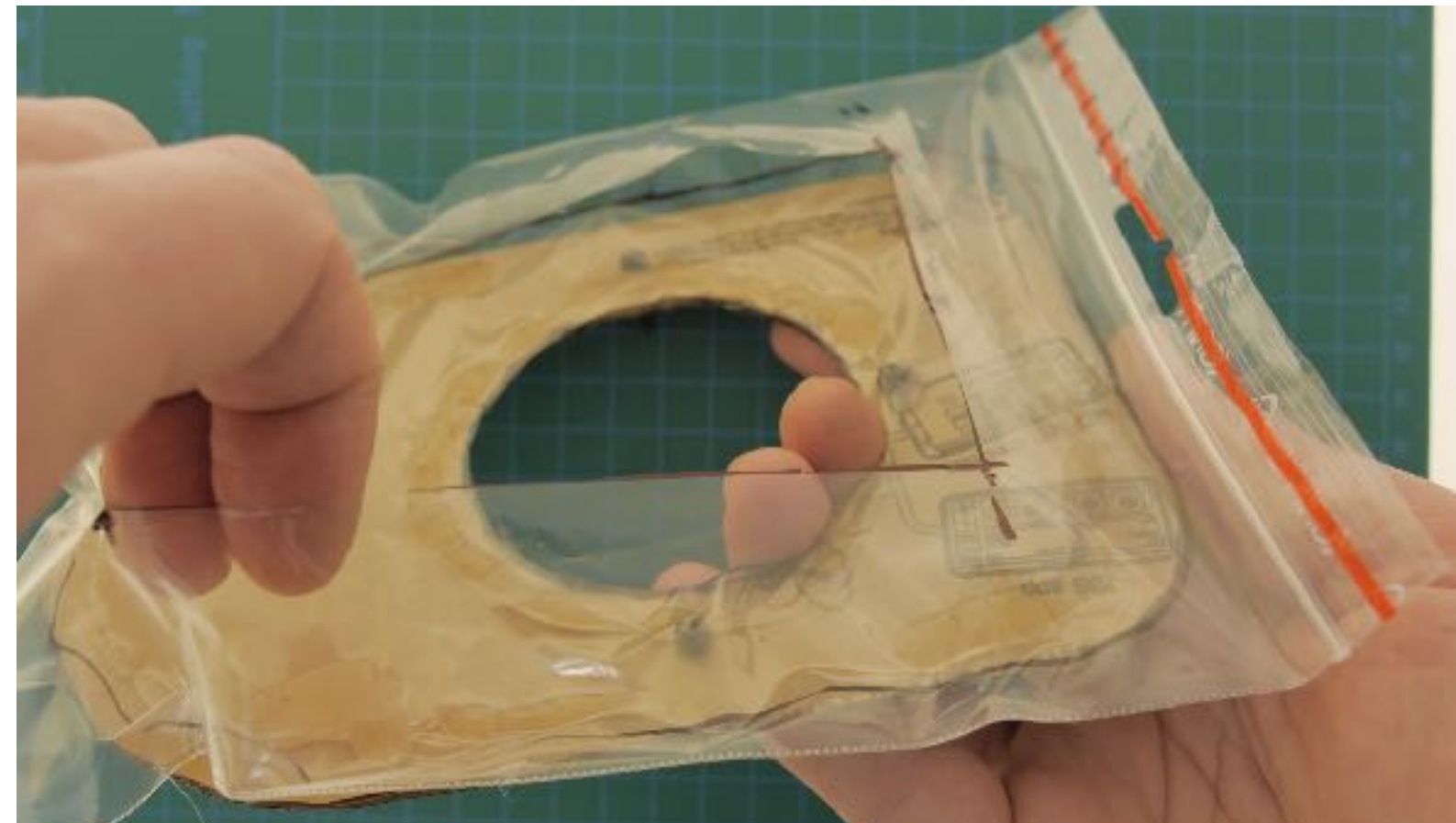
# Making the raft

Tools:

Parts:



Glued raft



- Your raft should now look like this!



- Zip the bag together to keep the air pressure inside when drifting



# Assembly

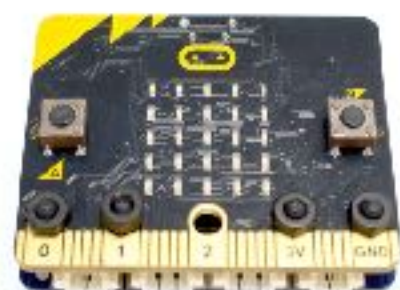
Tools:

Parts:

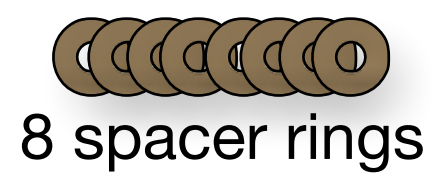
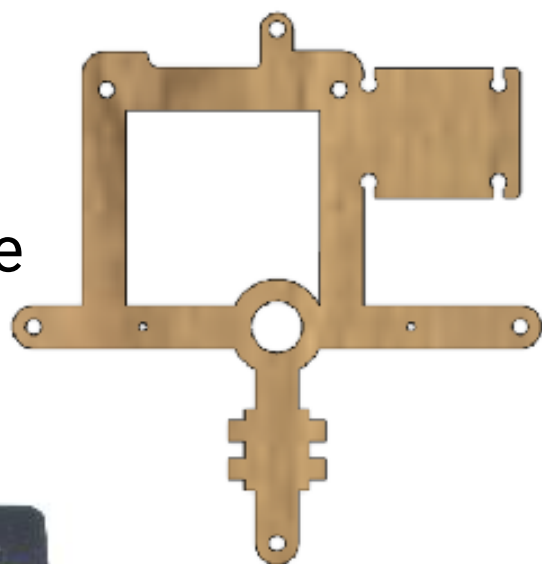


Glued raft

Base frame



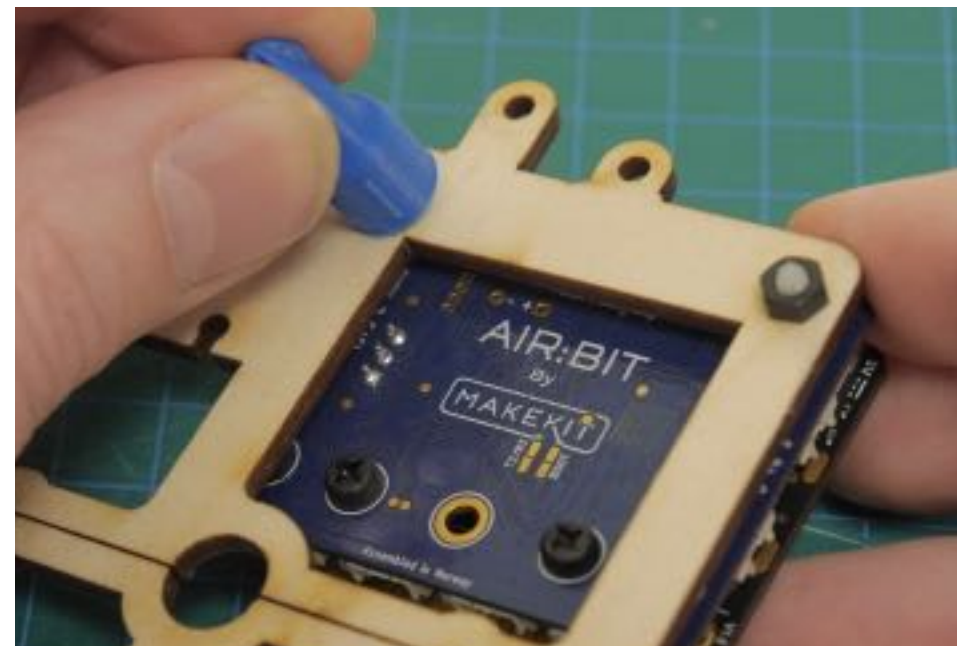
Control board assembly



8 spacer rings



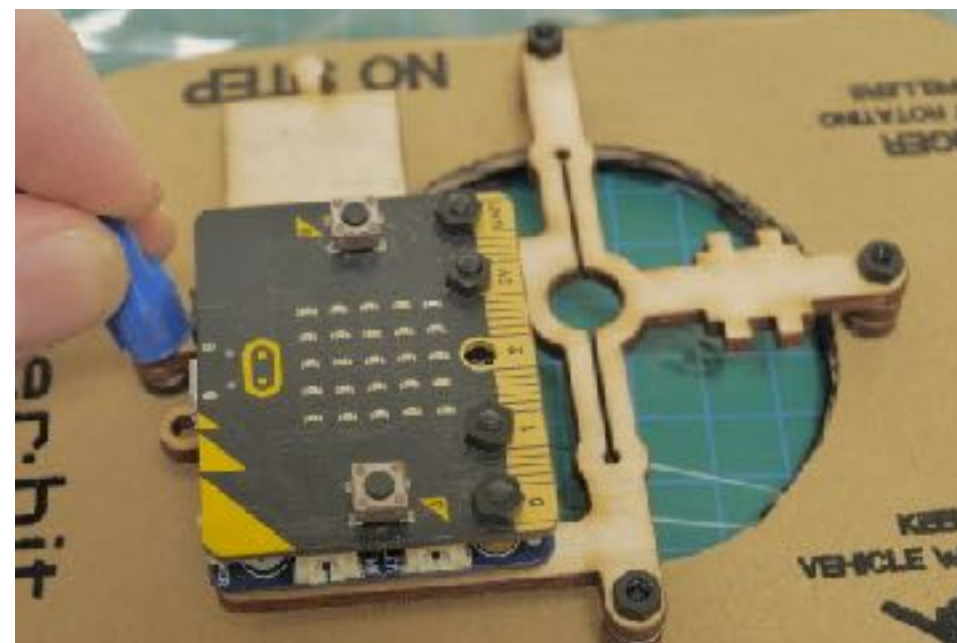
4 nylon bolts



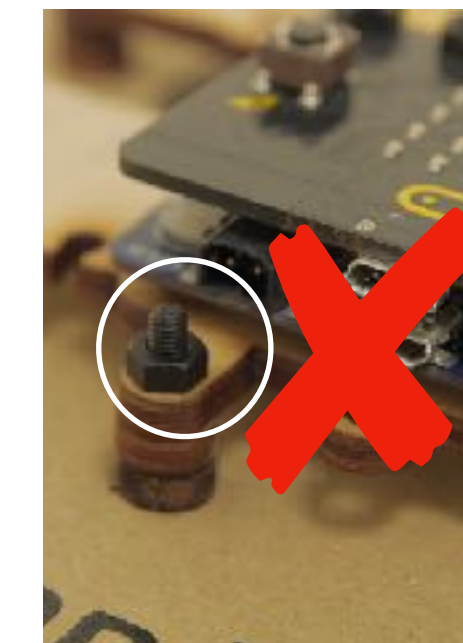
- Mount the control board assembly to the base frame



- Place two spacer rings on each screw



- Screw on all four bolts



- The screw can not go above above the nut as this can block the battery plug.



- If the screw is too long, cut it with pliers.



# Assembly

Tools:

Parts:



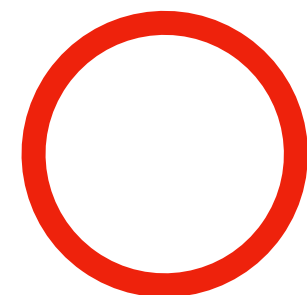
2 angle connectors



Motor holder



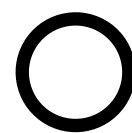
Servo



Large o-ring



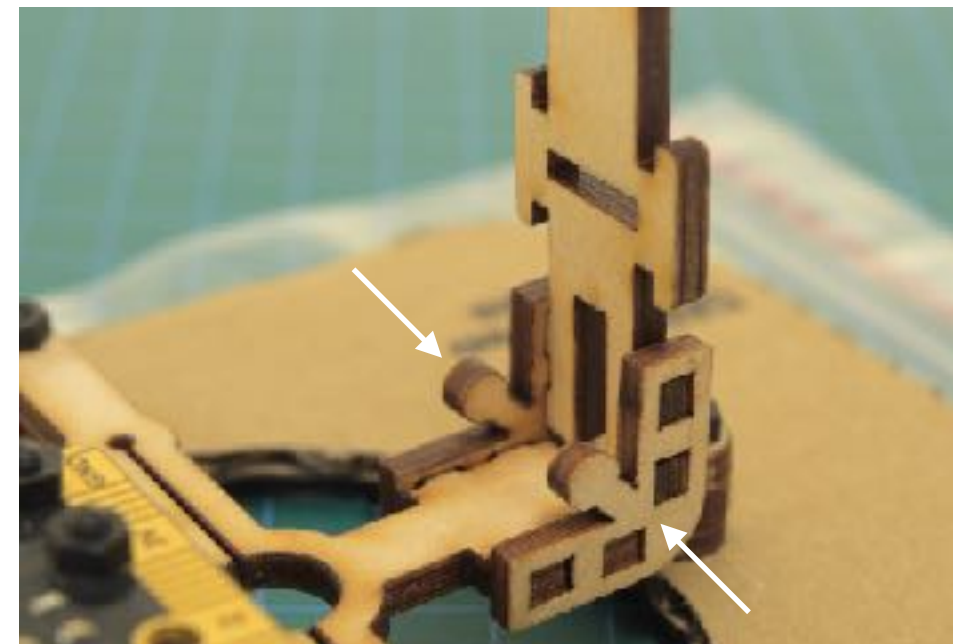
Servo horn



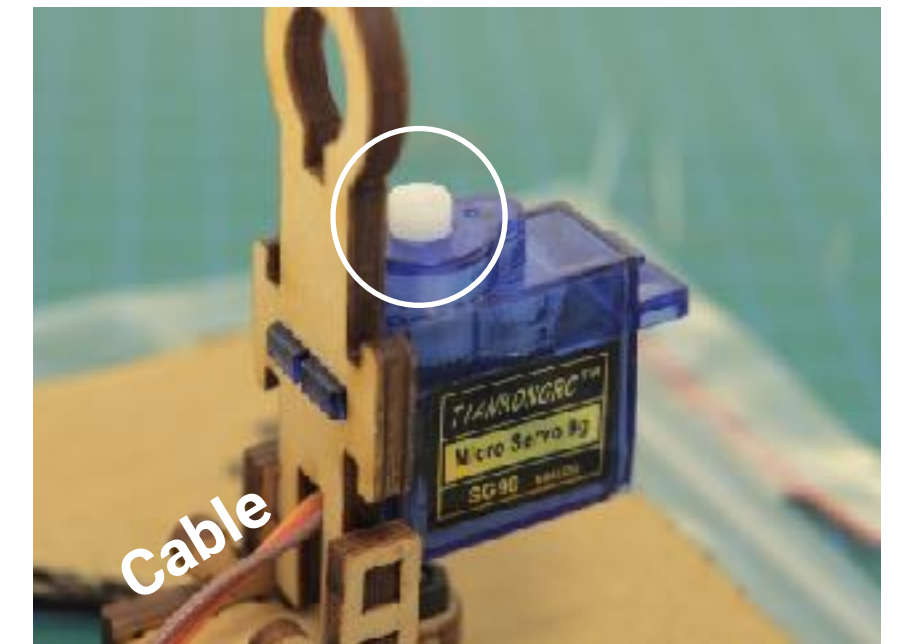
Small o-ring



Tail fin holder



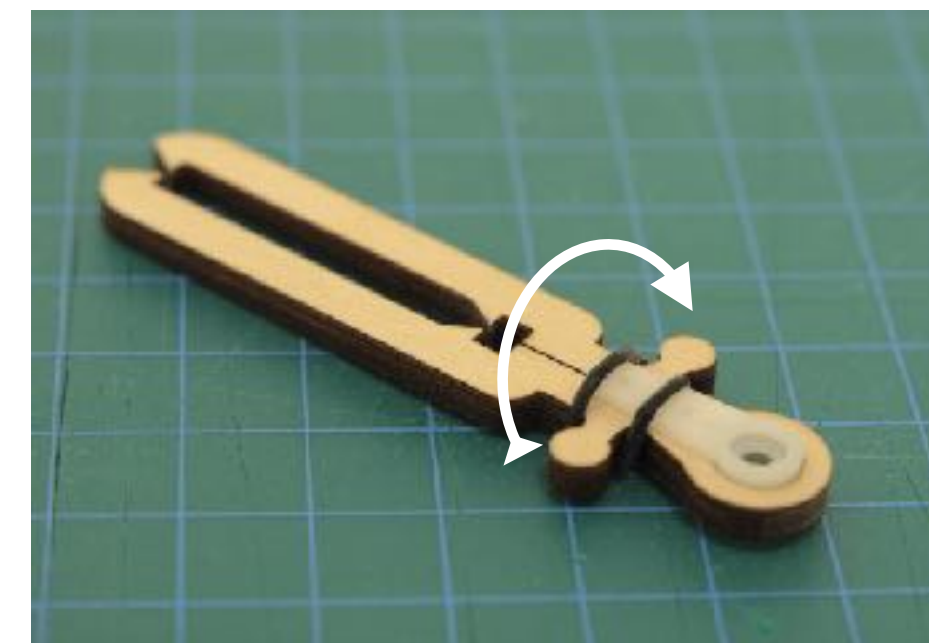
- Use the angle connectors to mount the motor holder to the base frame



- Insert the servo and pull the cable trough. The servo head (white circle) should be on the left side.



- Secure the servo with the large o-ring



- Insert the servo horn into the tail fin holder
- Secure with a small o-ring



# Assembly

Tools:

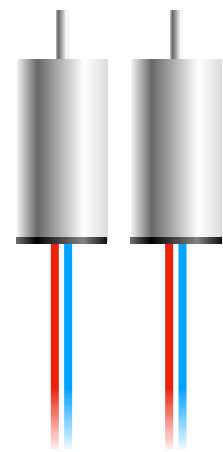
Parts:



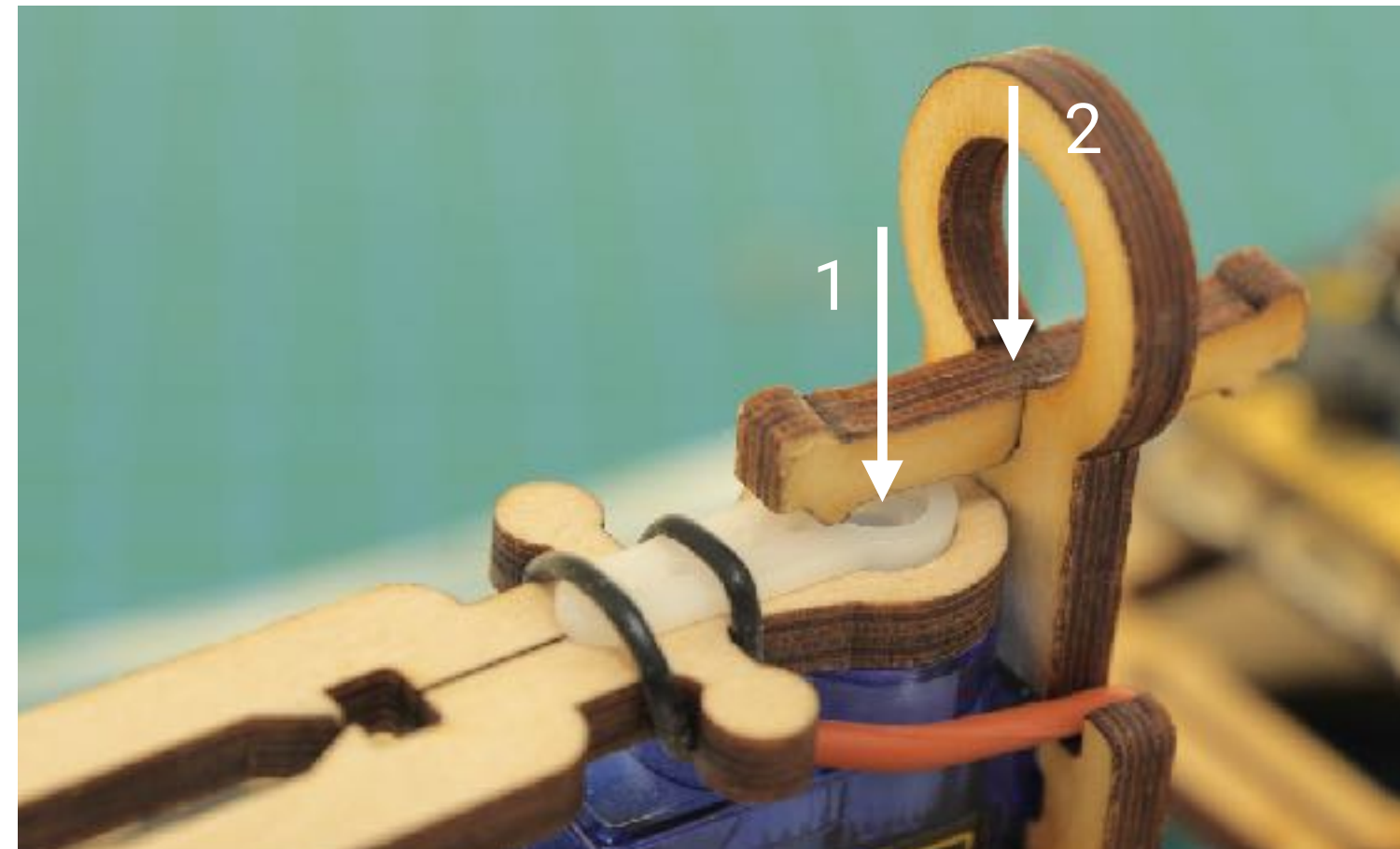
Tail fin assembly



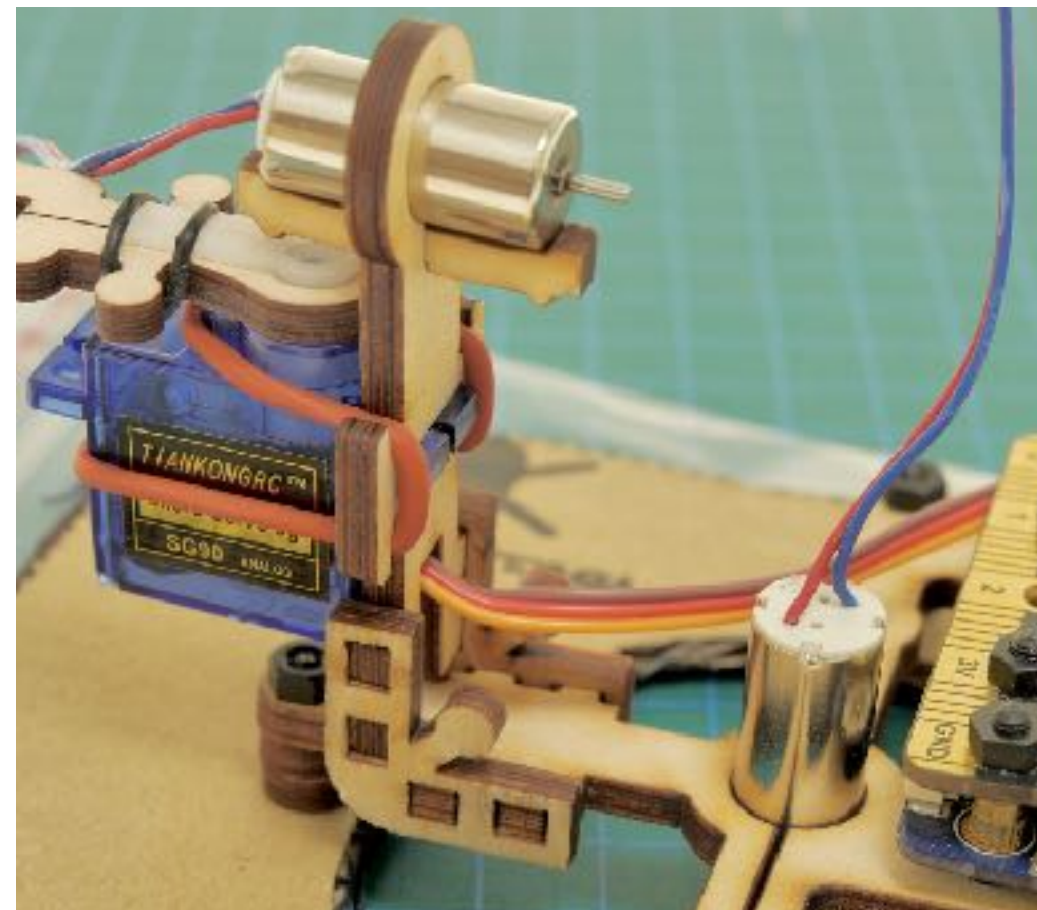
Wedge



2 motors



- Press the tail fin assembly onto the servo head (1). Make sure it sits firmly
- Insert the wedge (2)



- Insert the 2 motors so they sit firmly



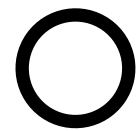
- Underneath, make sure the motor is flush with the base frame and doesn't stick out too much.



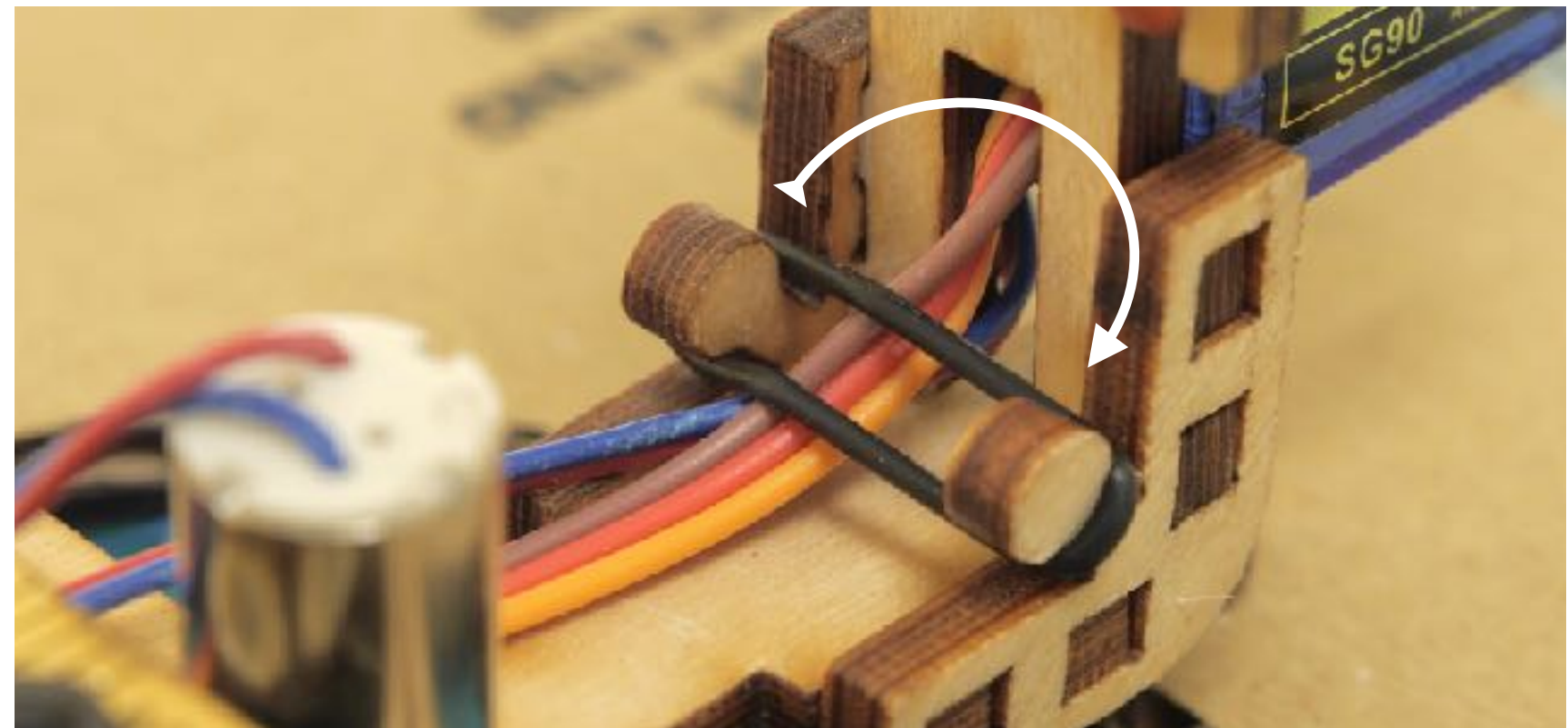
# Assembly

Tools:

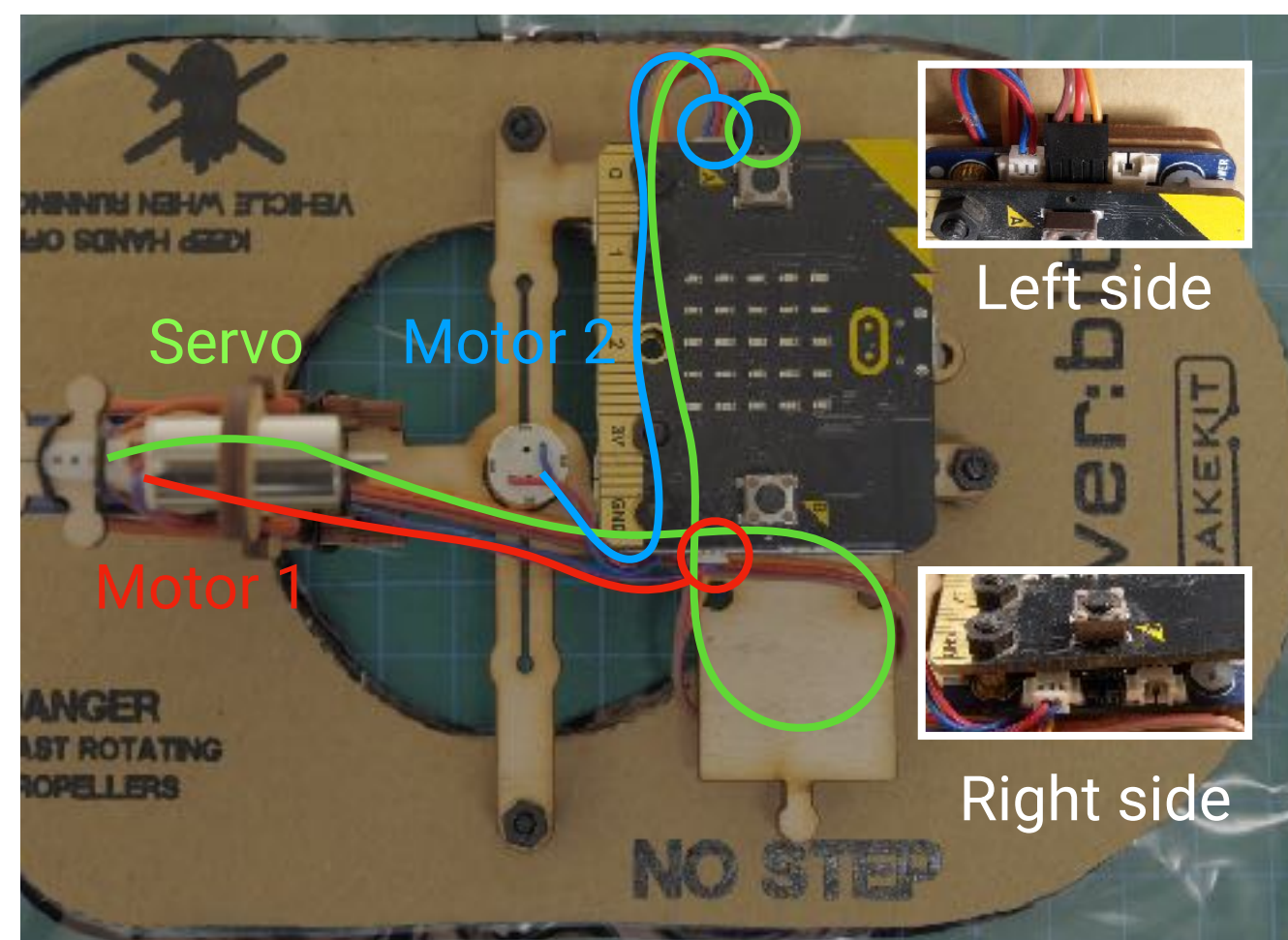
Parts:



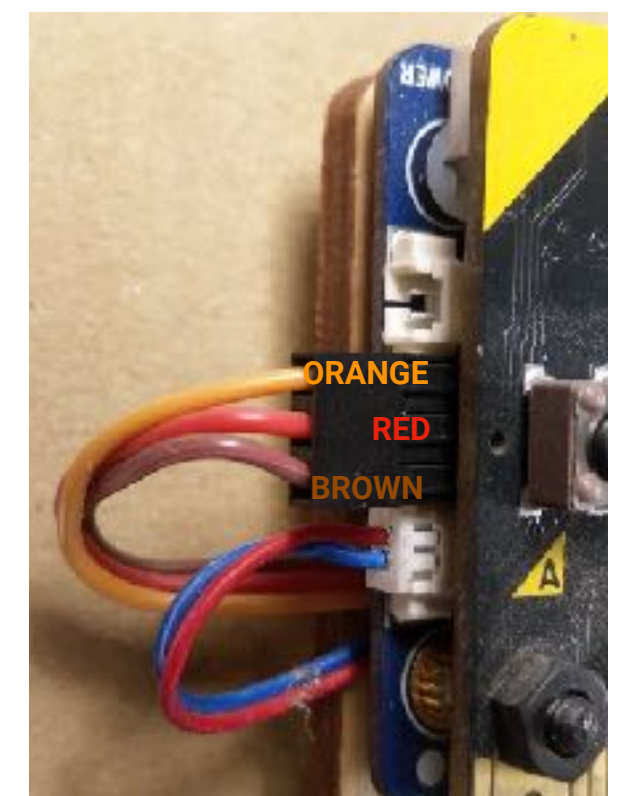
Small o-ring



- Pull the small o-ring over the motor cable and the servo cable to keep them away from propeller motion



- Organise and tidy up the cables.
- Plug motor 1, motor 2 and servo according to the illustration



- Make sure to plug the servo plug the correct way regarding the colors on the cables.



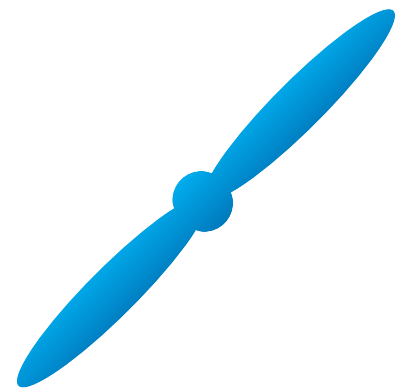
# Assembly

Tools:

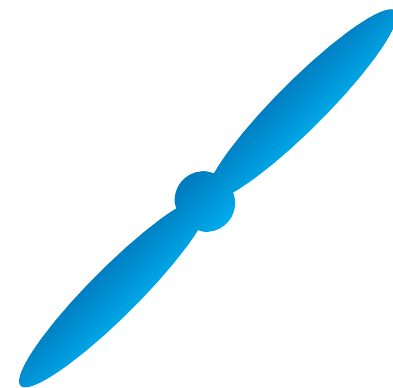
Parts:



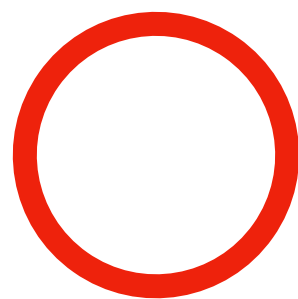
Tail fin



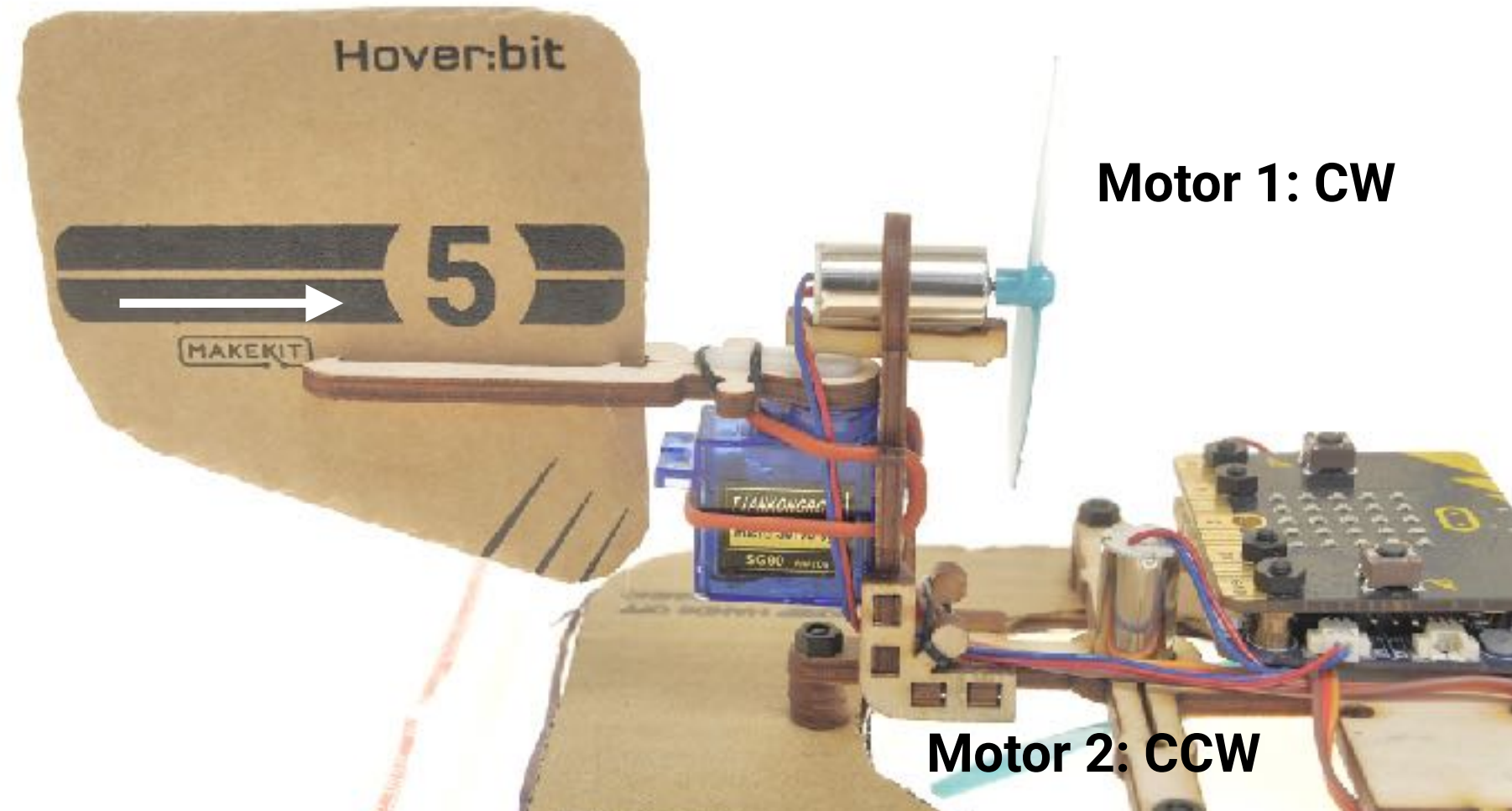
1 CW  
propeller



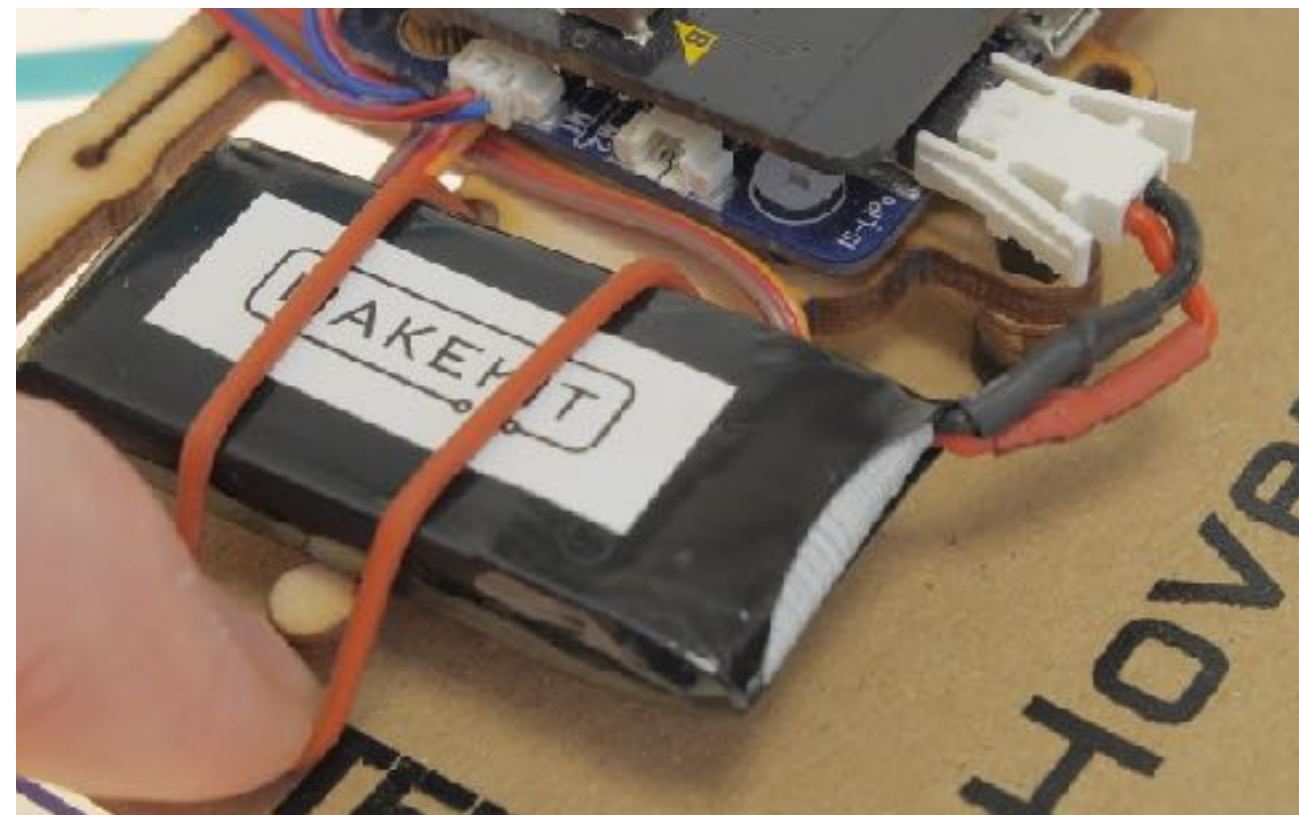
1 CCW  
propeller



Large o-ring

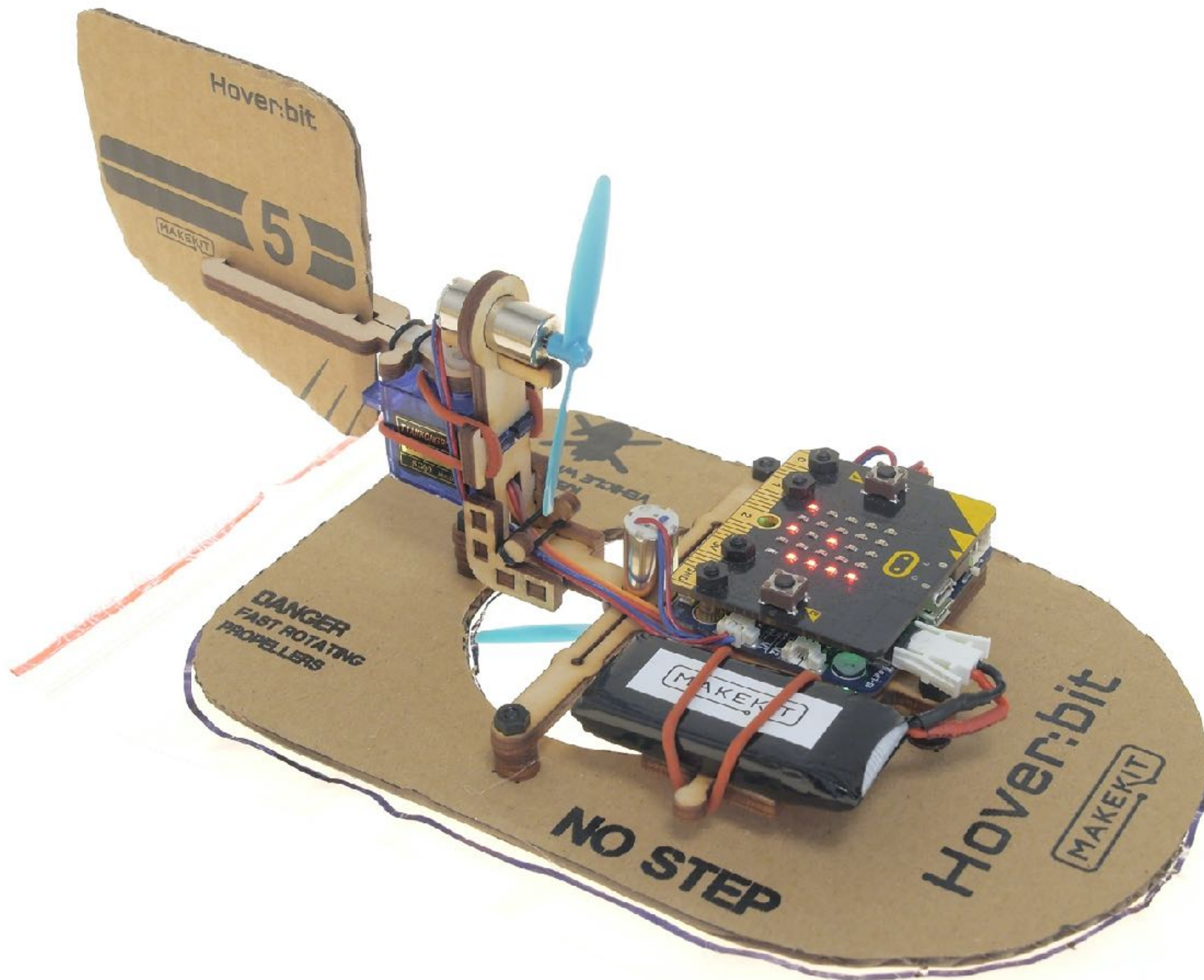


- Slide the tailfin into the tail fin holder
- Attach a CW propeller at motor 1
- Attach a CCW propeller at motor 2



- Connect the battery into the grey plug
- Secure the battery with the large o-ring







# Contact:



[www.makekit.no](http://www.makekit.no)



[henning@makekit.no](mailto:henning@makekit.no)



[makekit](https://www.facebook.com/makekit)



[gomakekit](#) (also twitter)

Get fast response at our facebook group:  
**[www.facebook.com/groups/goairbit/](https://www.facebook.com/groups/goairbit/)**