



WONDER:KIT

EXPLORER + REACTIONBIT



#### Introduction

**Wonder:kit explorer** is the basic package in the wonder: kit concept and will be used together with a micro:bit.

It provides basic experience with physical components such as LED, servo (movable arm) and buzzer (speaker), and connects these to micro:bit sensors.

**Reaction:bit** is a reaction time tester based on a switch, buzzer and code.

In addition to this guide, there is an inventor concept where students will create their own inventions.

Before you get started, you should know some basic uses of the micro:bit:

- Easy coding with makecode (makecode.microbit.org)
- · Simple codes, we recommend "Flashing Heart" and "Rock, paper, scissors" as a minimum
- · Connection and transfer of the code to the micro:bit

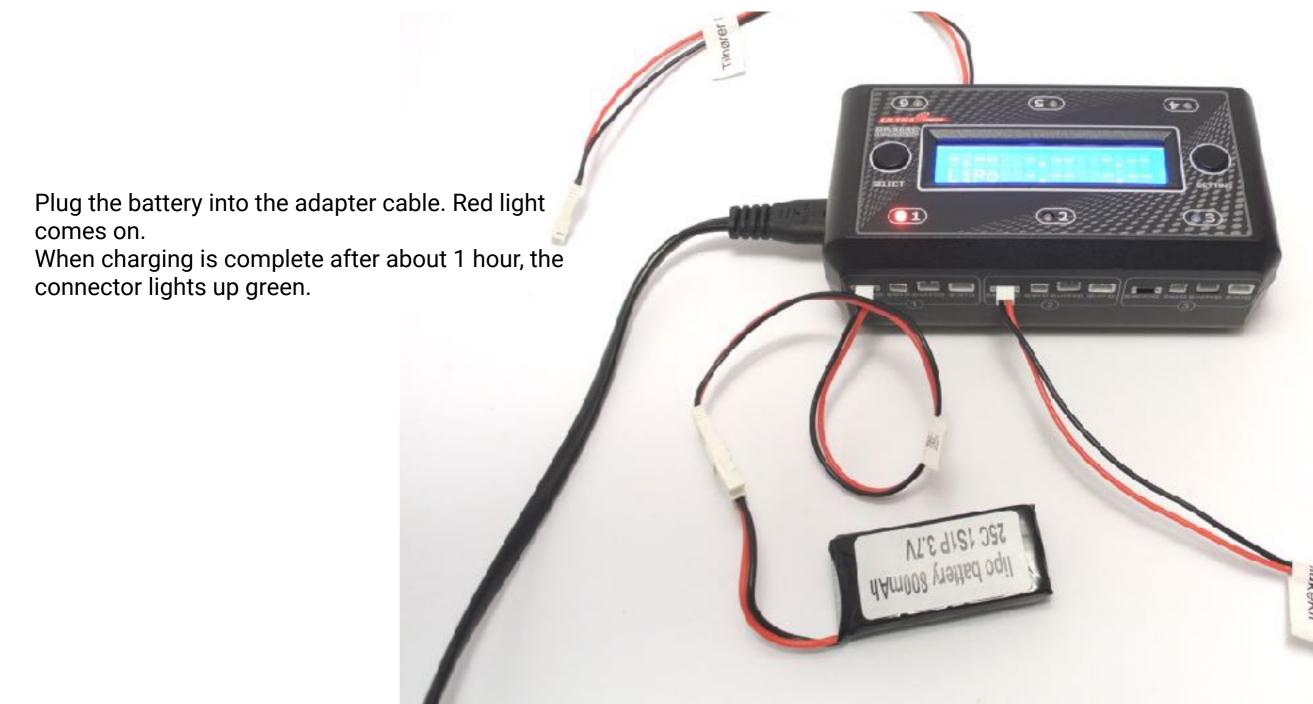
More about this can be found in our guide Introduction to micro:bit



### **Content**

Content	Page	Difficulty
Charging the battery	4	Easy
Explorer: Assembly	6	Easy
Code tasks with LED and buzzer	13	Easy
Servo engine	25	Medium
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# Charge faster

Set the charger to charge twice as fast (from two to one hour to charge empty battery)

Press **Select**. "Current 0.5A" is displayed. Press **Setting** 5 times. "Current 1A" is displayed Hold **Setting** until "Save setting" appears.

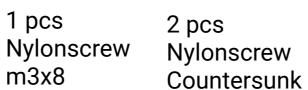


# Assembly EXPLORER

# **Parts**

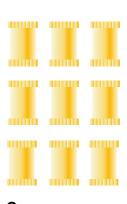








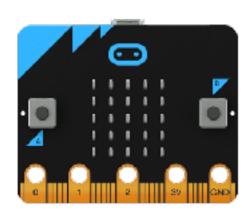
4 pcs nylonnuts knurled barrel m3



9 pcs nuts



2 pcs crocodile clips In different colors



micro:bit



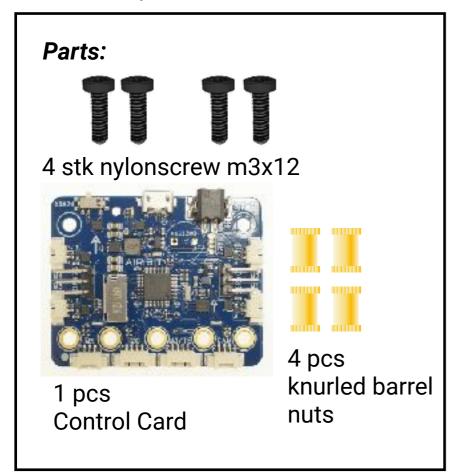
Control card



# Tools needed:

- Small Phillips screwdriver
- Scissor or wallpaper knife (for cutting aluminum foil for first time installation for the reactionbit)

**Tool:** Phillips screwdriver



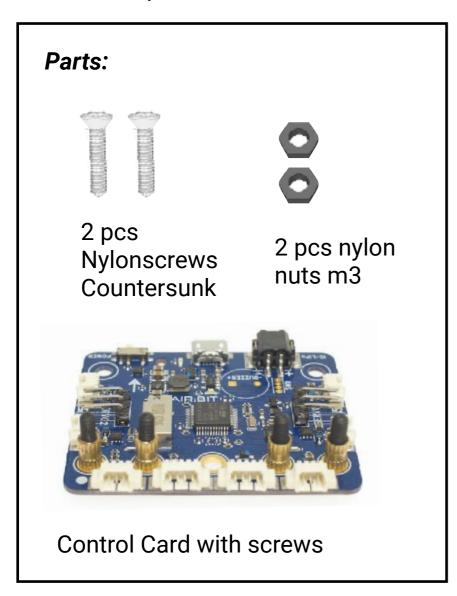


Tighten the barrel nuts with the nylon screws. They must be screwed "finger tight":

- Tight enough to make live contact with the control board,
- Not so hard that the screw or control board is damaged.

NOTE! Check that the nuts are tight so that they have good contact with the control board. They must conduct power to the micro:bit.

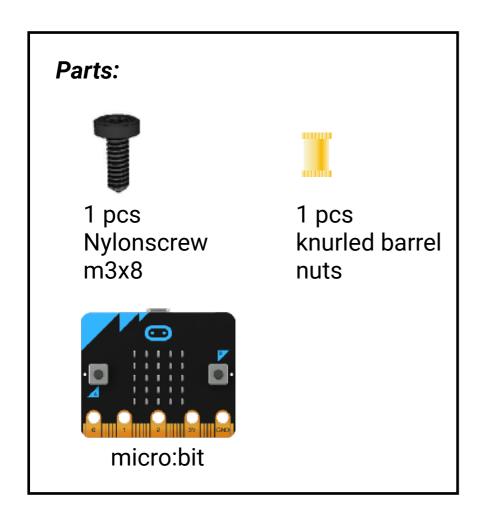
**Tool:** Phillips screwdriver, and a socket wrench

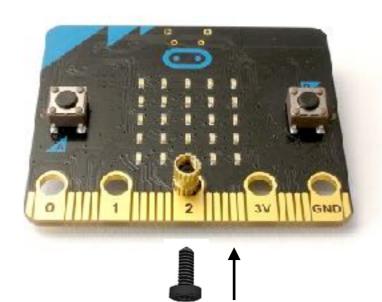




Fasten the nylon screws with nuts as shown in the picture.

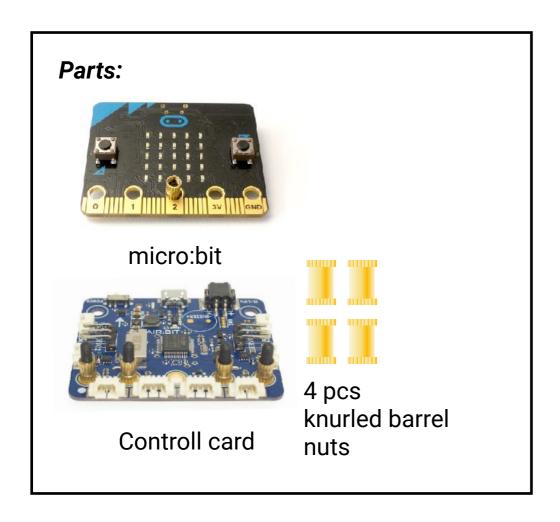
**Tool:** Phillips screwdriver

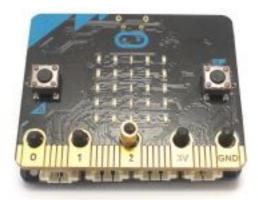




Pull the screw up through P2 and screw the barrel nut on the top

#### Tool:







- Place the micro:bit over the control card so that the screws go through the holes. The screen should point up.
- Tighten the four barrel nuts
- Make sure they are tight enough.

NOTE! Check that the nuts are tight so that they have good contact with the control board. They must conduct power to micro:bit.

# Code tasks EXPLORER

# Light indicator, LED

An LED is a diode that emits light.

Diodes have the property that the current can only go one way. Therefore, we must give them power in the right direction for it to shine.





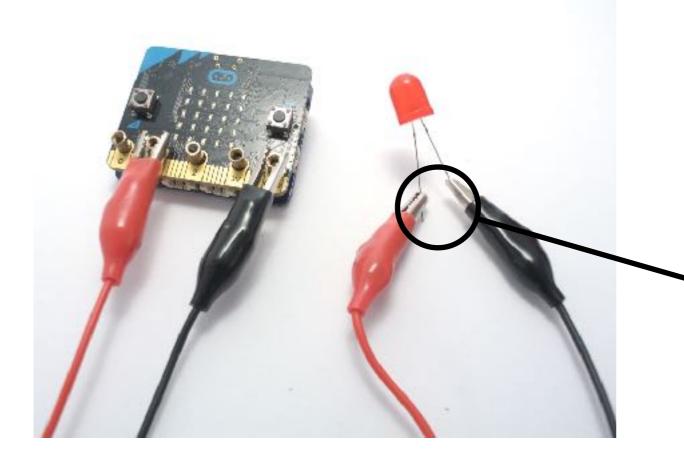
#### You need:

Two crocodile clips, wonder:bit + micro:bit device, LED, USB cable

# Make a light switch

Connect the LED with two crocodile clamps as shown in the picture. The long leg goes to P1 and the short leg to GND (ground). Long leg means positive, and we will send positive current from P1. Make sure that the metal on the two crocodile clips does not come into contact with each other. Then we get a short circuit, which can damage the micro: bit.



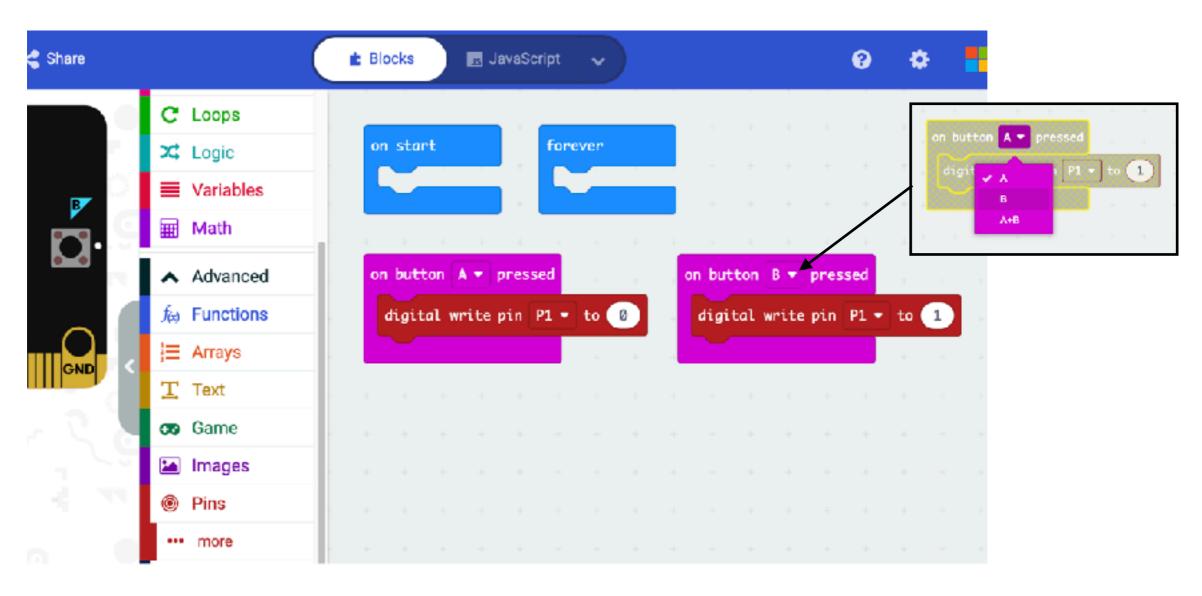


"Long legs is a positive thing"

These must not touch each other as it may cause a short circuit

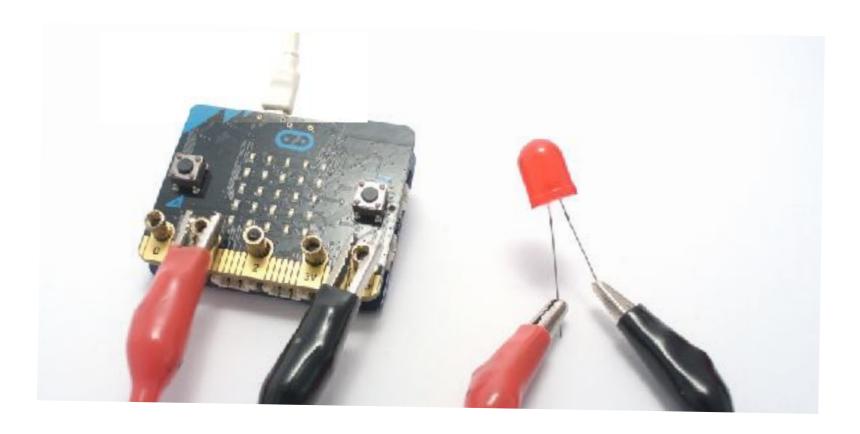
# Code the light switch

Grab two "on button A" and change one to "on button B" Go down to Advanced - Pins and select digital write 0 in "on button A" and digital write 1 in "on button B"



# Test the light switch

Download the code and press both A and B in turn.

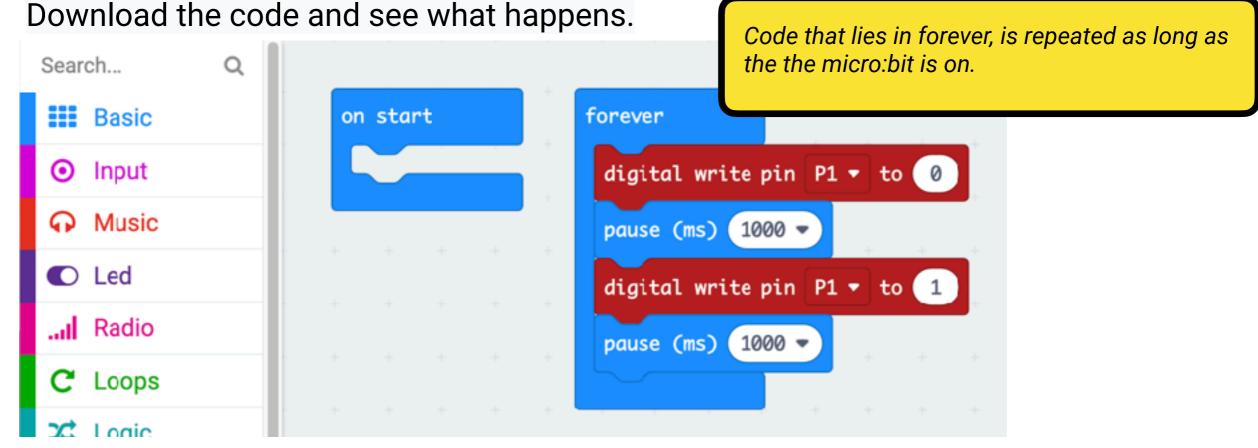


#### What happens?

When we press the B button, we turn on the power that goes out of P1. This is enough to make the LED light up. When we press A, it goes out again.

# Code a turn signal

We can make our LED flash automatically by using the forever loop and pause function. First we turn off the power. Then we wait a second (1000 milliseconds). Then we turn on the power, and wait another second, before the code repeats itself automatically.



#### Try this:

Change the pauses to ex. 500 ms or 2000 ms, and see what happens.

# Buzzer (høyttaler)

En buzzer er en slags høyttaler. Den omformer elektriske signaler til hørbare lydbølger.

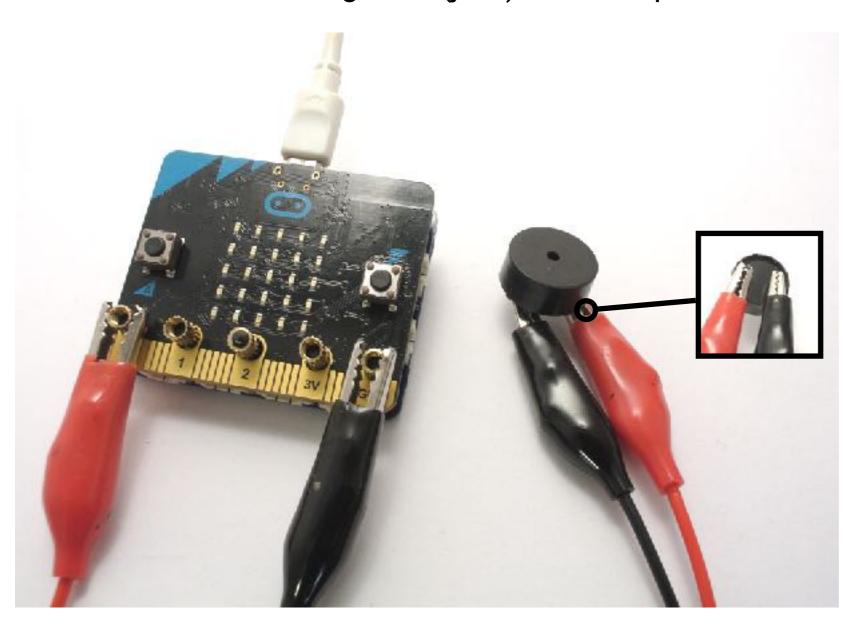


#### **Du trenger:**

To krokodilleklemmer, wonder:bit+micro:bit enheten, lysdiode, USB-ledning

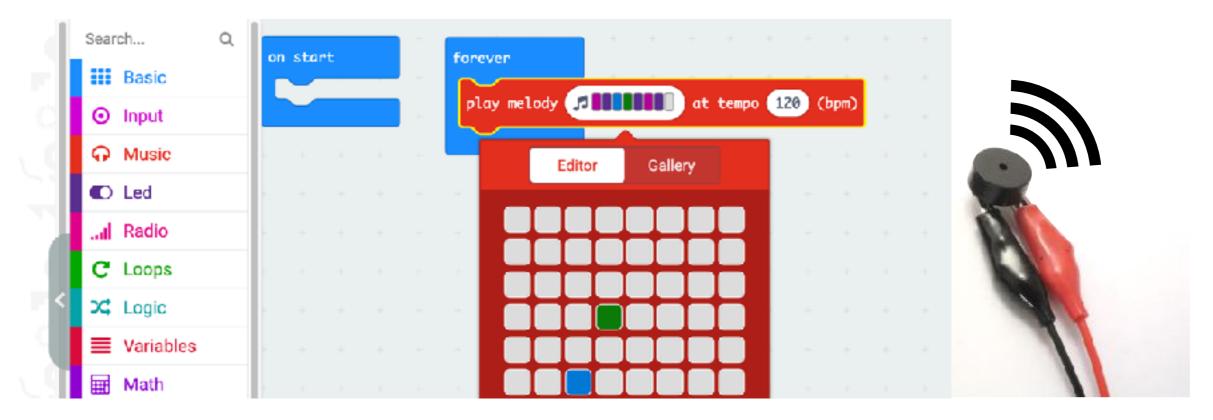
# Lyd med buzzeren

Koble buzzeren til P0 og GND (jord) som vist på bildet.



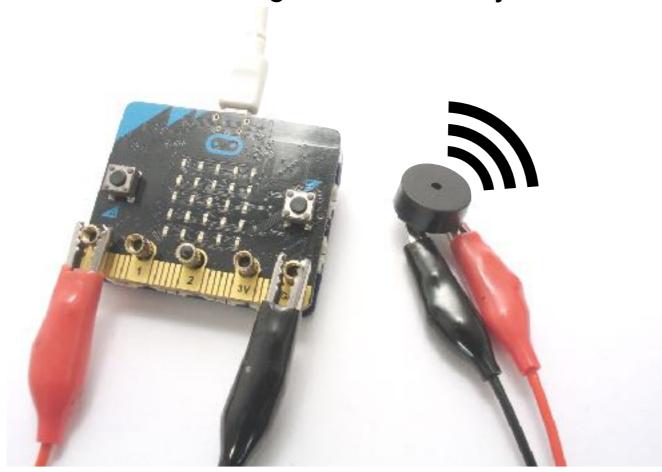
## Kode buzzeren

Fra music-kategorien henter du ut en "play melody". Klikk i melodien og komponer din egen sang, eller velg en ferdig i galleriet. Denne legger du i forever-løkken.



### Test buzzeren

Last over koden og se hva som skjer

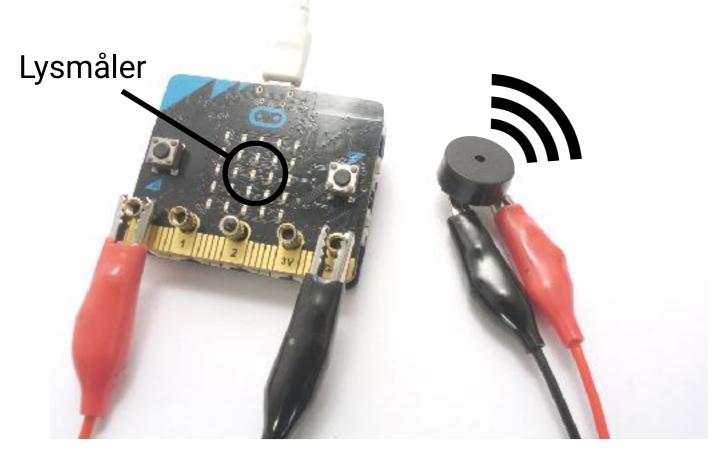


#### Hva skjer?

Når vi bruker "play melody", sendes elektriske signaler ut fra gjennom P0 og tilbake til jord. Signalene gjøres om til lydbølger i buzzeren, som oppfattes som ulike toner i øret.

# Lag en theremin

En theremin er det eldste elektroniske instrumentet, og kan spilles ved kun ved å bevege hendene over en føler. For å måle håndbevegelser, kan vi bruke lysmåleren på micro:bit.



Lysmåleren gir oss et tall mellom 0 og 255. Jo mer lys, jo høyere tall.



Russeren Leon Theremin oppfant thereminen i 1919 (Wikimedia commons)

# Try the thermine

Move your hand up and down, or from side to side over the micro:bit light meter. What happens to the tone?

#### Things to try:

- Light with a flashlight on the sensor
- Turn on or off or dim the ceiling light - do you hear the difference?
- Place your thumb over the opening on the buzzer.
   What happens to the sound? Can this be used to shape the sound or music you make?
- Can you find more ways to play the instrument?

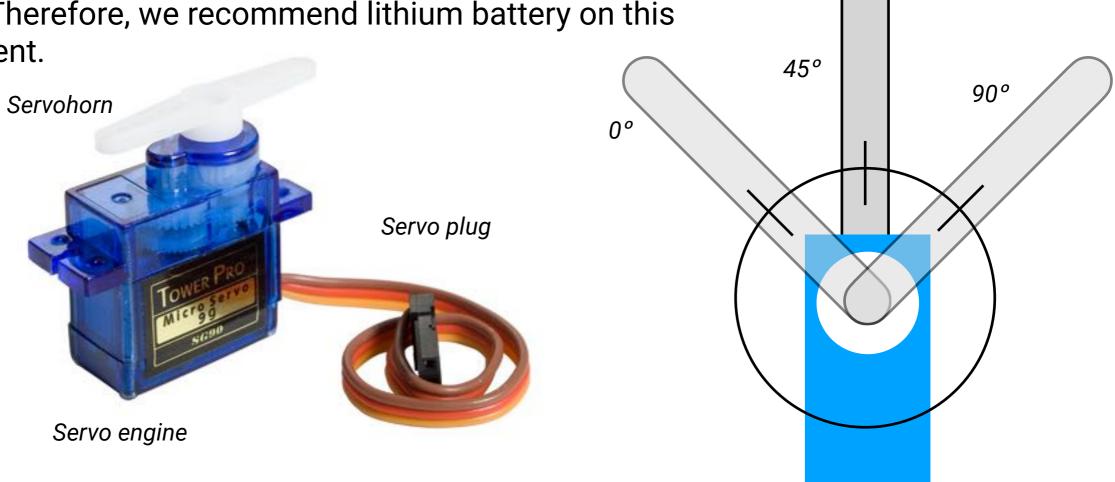


## Servo engine

A servo engine is an electromechanical arm that can move at a given angle, based on a signal.

The servo engine needs a little more energy than led and buzzer. Therefore, we recommend lithium battery on this

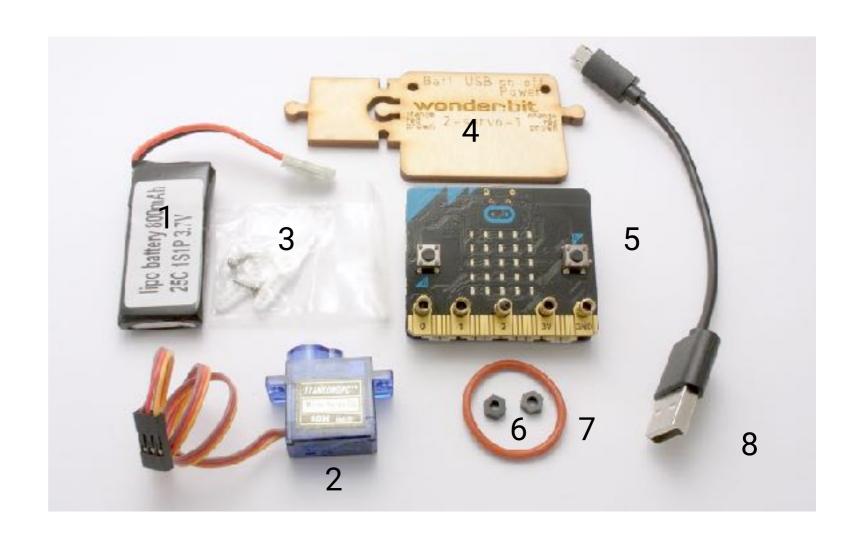
experiment.



# Servo engine

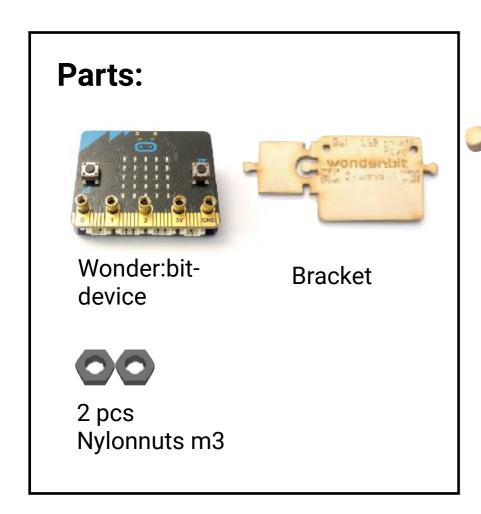
#### You need:

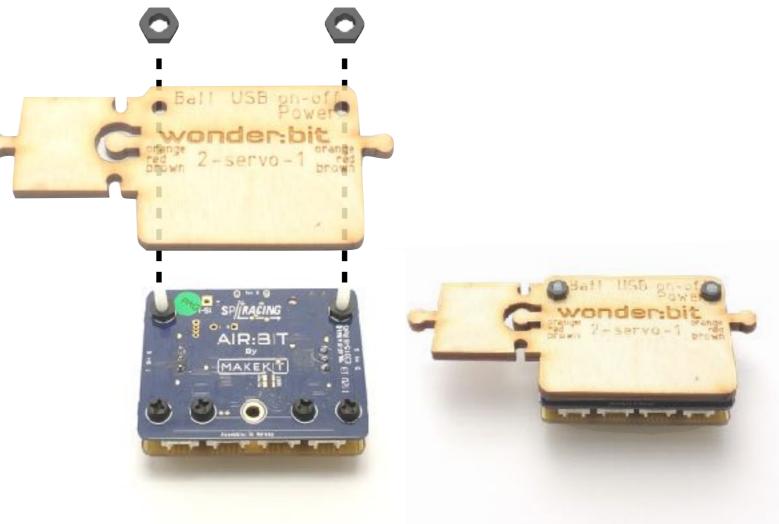
- 1. Lithium-battery
- 2. Servo engine
- 3. Servohorn
- 4. Wonder:bit bracket
- 5. Wonder:bit-device
- 6. Two nuts
- 7. Large rubber band
- 8. Micro USB-cable



## **Bracket**

Tool: Socket wrench 5,5mm

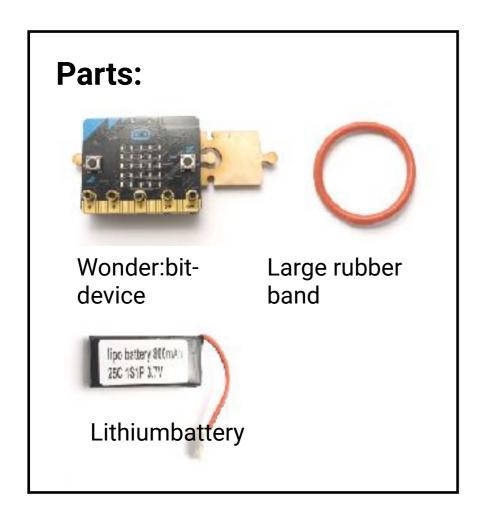


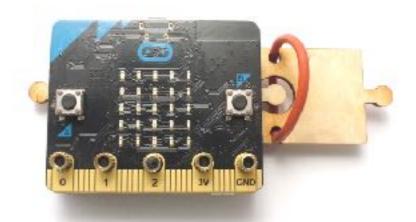


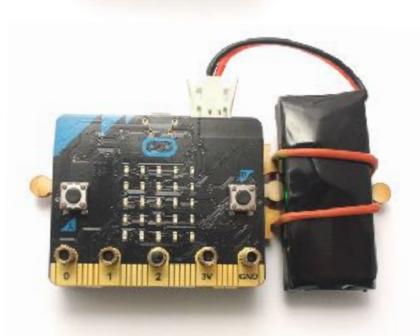
Turn the wonder:bit unit upside down and fasten the battery holder (bracket) with two nuts.

# **Battery**

Tool:



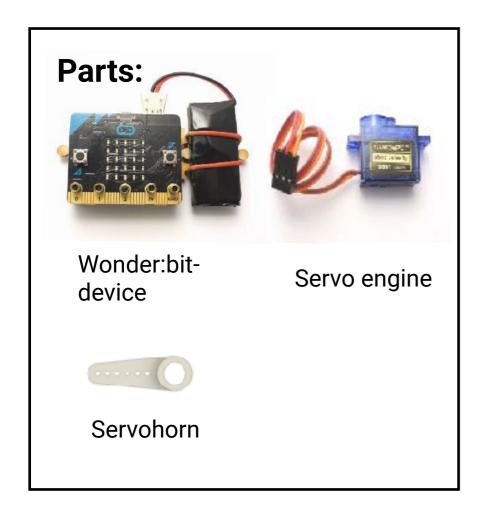


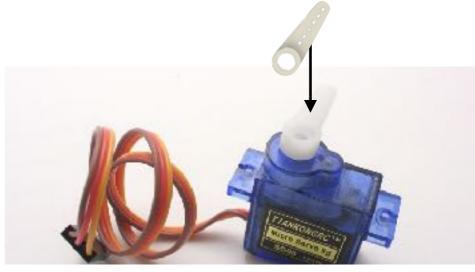


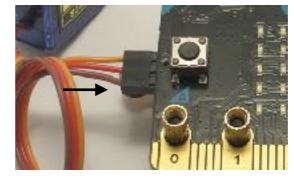
- · Turn the wonder:bit device back.
- Insert the rubber band into the slot, pull it over the battery and attach it to the knob on the right side.
- Plug in the battery (gray or white plug)

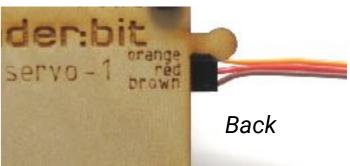
## Servo

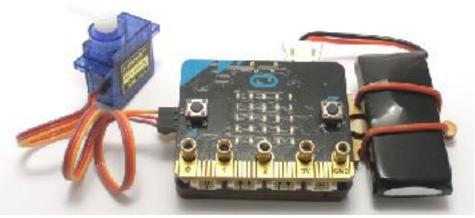
#### Tool:









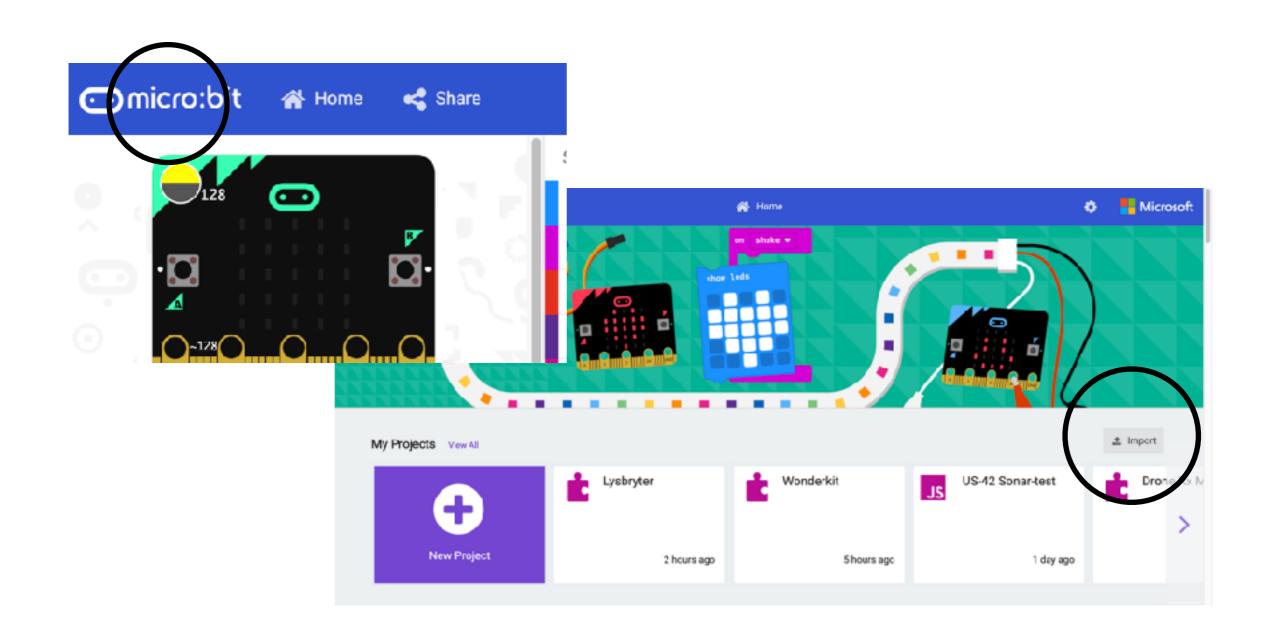


- Press the servo horn into place on the servo engine
- Connect the power plug to the wonder:bit unit
- Notice the colors when you plug in, orange up and brown down.

Front

## Code the servo

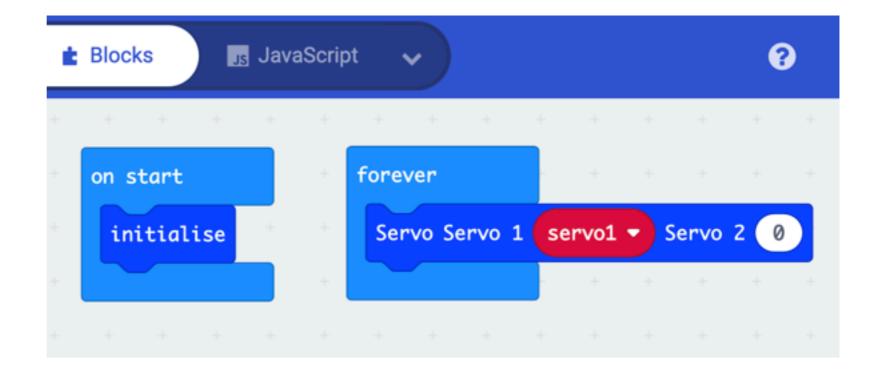
To control the servo, we need the wonderbit-library. Download wonderbit-servo.hex from where you found this guide. Click "micro:bit" to get to the home page, then "import".



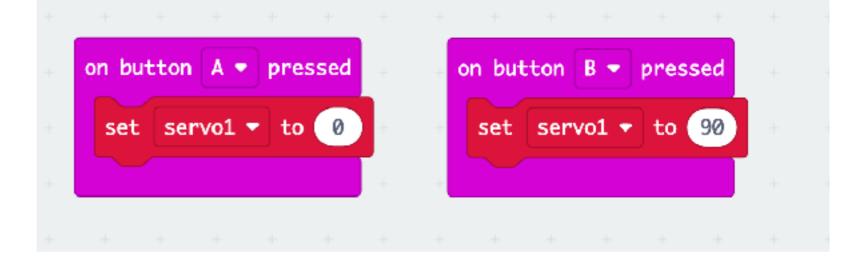
## Code the servo

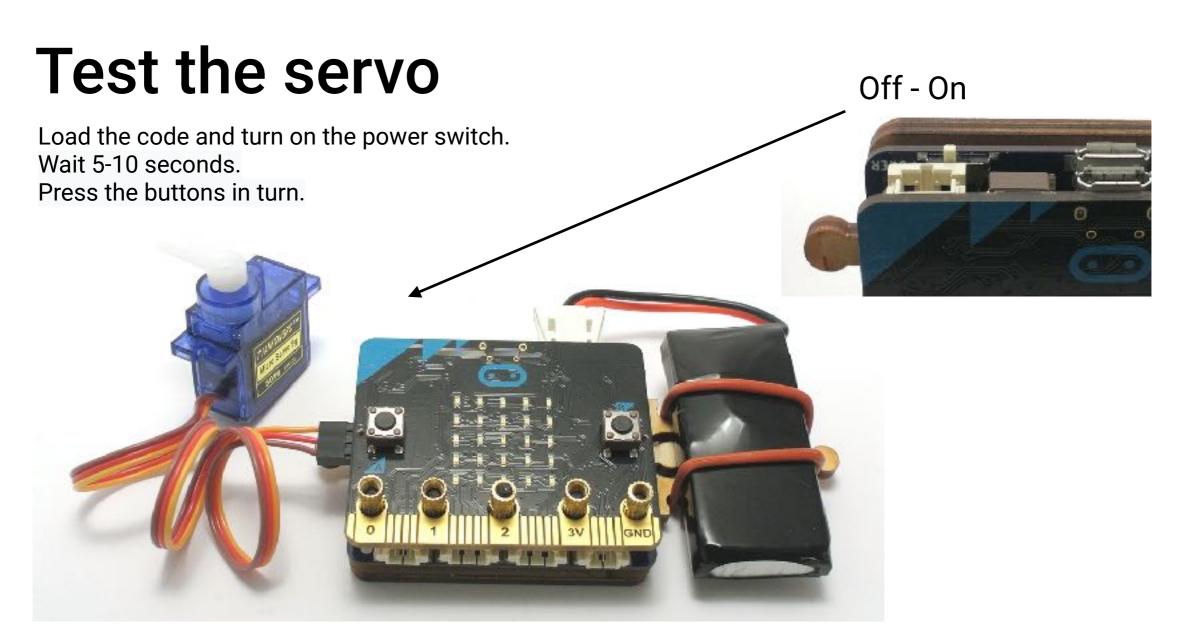
We start with the code below. Servo1 is a variable, which we must change to control our servo.

Here is the code we start with:



Add this code:





#### What happens?

When we press the buttons, we change the angle of the servo1 variable. This is transmitted as a signal to servo engines, which move the horn to the desired position.

#### If it does not work:

Disconnect the usb and turn the power switch on and off

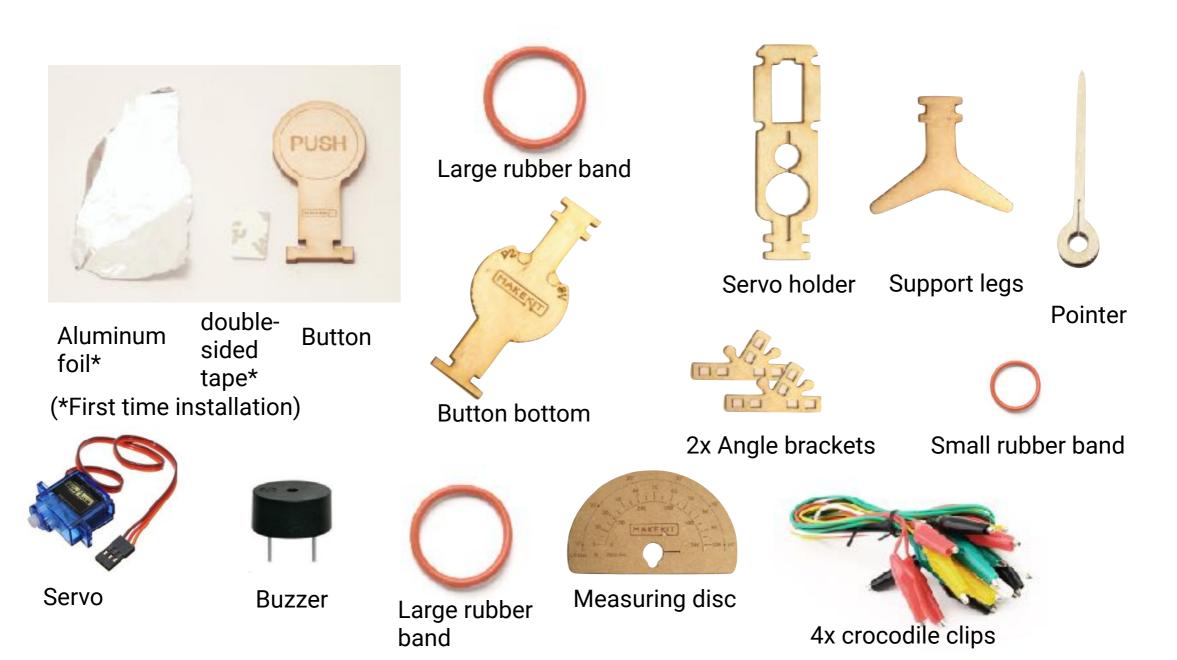
Check if the servo plug is connected correct, with orange up and brown down.

Check if there is power on the control board (green light)

The orange light below P0 should stop flashing after about 7 seconds. If not, check/tighten the barrel nuts (gold colored)

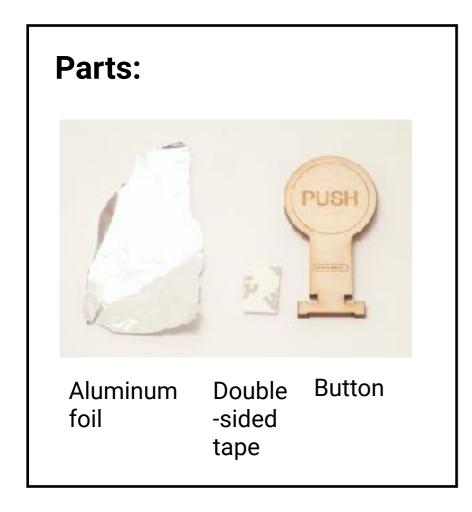
# REACTION:BIT

# Parts, reaction:bit



## **Button**

Tool: Wallpaper knife or scissor





Attach the double-sided tape to the underside of the button, at the very top.



Cover the tape with aluminum foil and cut off the extra foil.

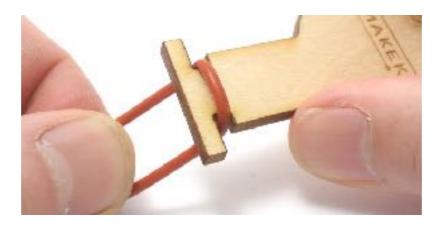


Result

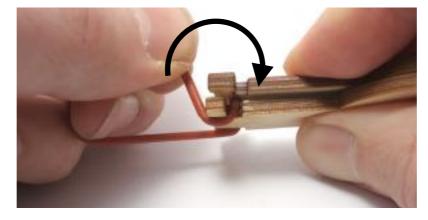
## **Button**

Tool:





Thread the rubber ring into the button base



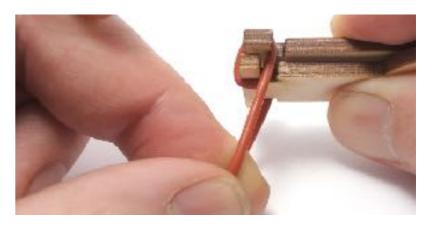
Pass the rubber ring around both knobs and back again.



Repeat on the other side so that it is symmetrical.



Place the push button on the top





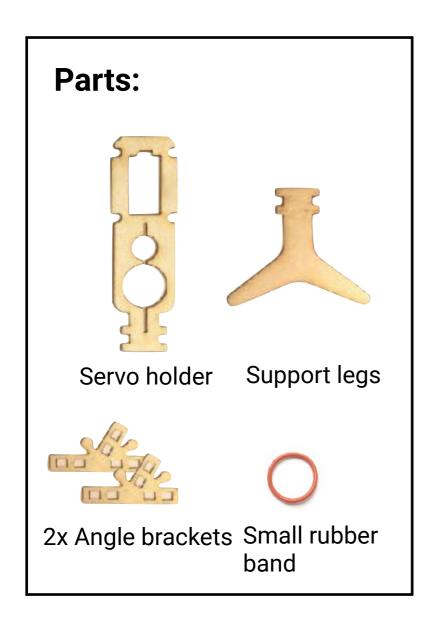
The back should be like this

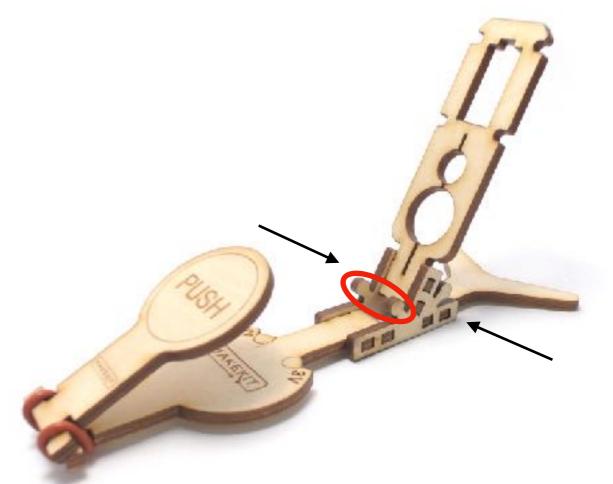


The button springs upwards

### Install servo holder

Tool:

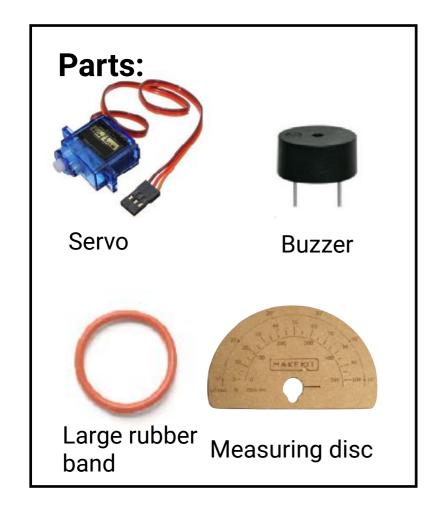


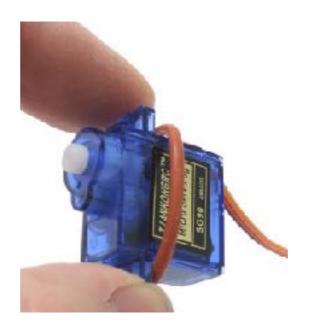


Attach the button to the servo holder and support legs with the angle brackets. If they do not stuck, you can use a small rubber ring between the fastening knobs (red ring)

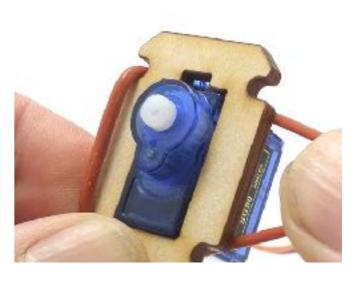
#### Install the servo

Tool:





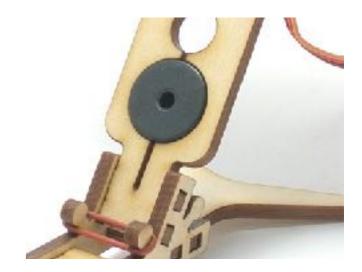
Pull the servo cord through a large rubber ring.



Push the servo through the bracket, with the gear up. Pull the rubber ring around it, so that it secures the servo.



Push the Measuring disc in place.



Push the buzzer in place.

## Wiring

Tool:

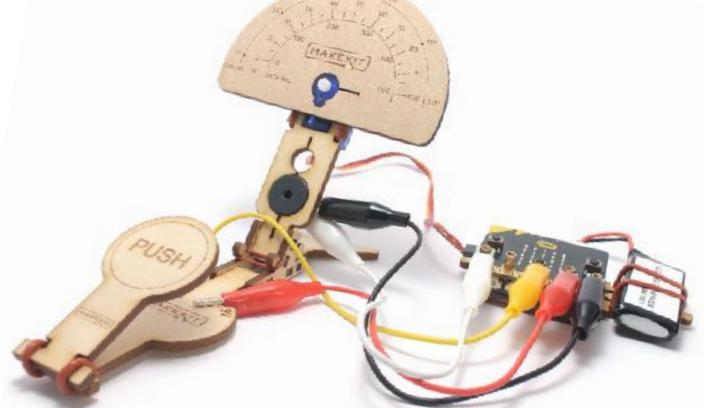




Fasten a yellow and a red crocodile clamp into the slots, yellow to P2 and red to 3V



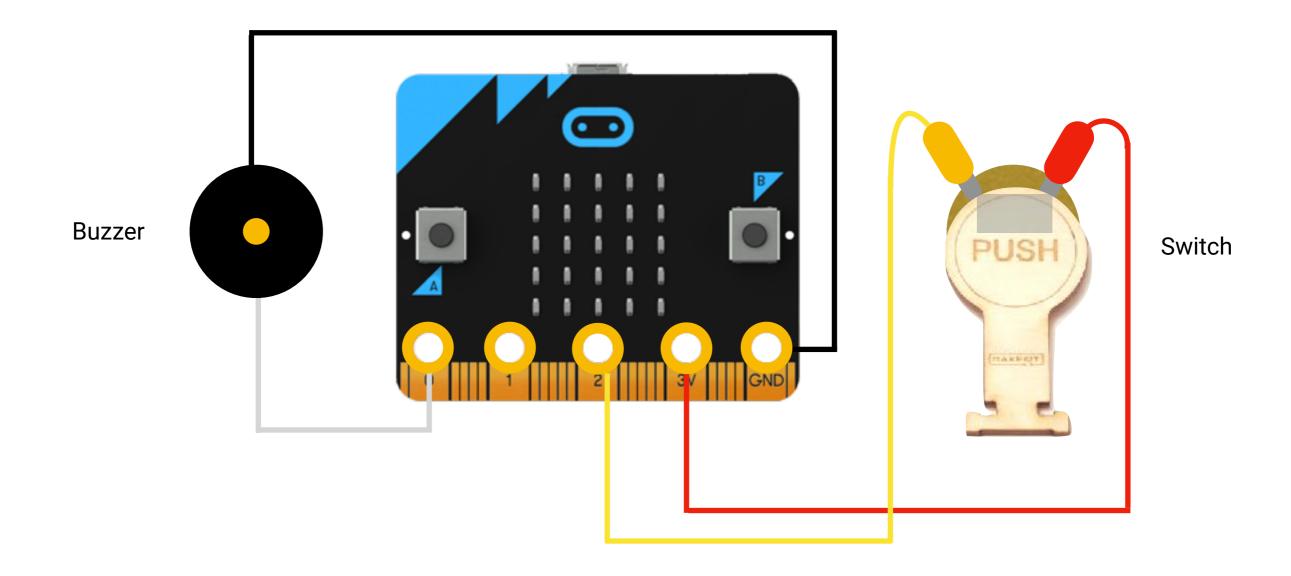
Connect the crocodile clips to the micro:bit, like this



Connect the other end of the yellow and red crocodile clamp to P2 and 3V

Connect the two legs of the buzzer to P0 and GND (ground) See wiring diagram on the next page

# Wiring diagram



#### Test the connections: Morse code

We can test our connections by making a Morse code device.

Use if-blocks, pin-blocks and music-blocks to create this code.

Digital read can be found under Advanced and Pins

Download the code for micro: bit and test.

When you press the button, you will hear a beep from the speaker.

If not, check the connections with the crocodile clips.



```
if digital read pin P2 ▼ = ▼ 1 then

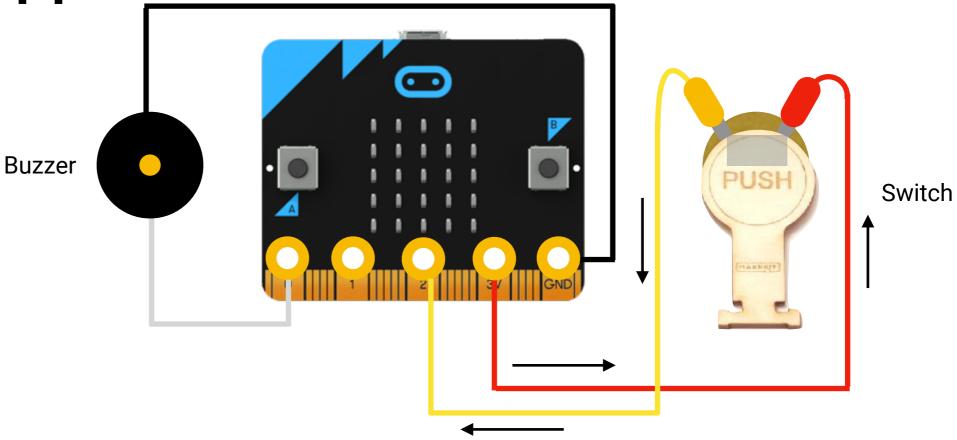
ring tone (Hz) High C

else 

rest(ms) 1/16 ▼ beat

⊕
```

What happens?



When you press the button, contact is made between the crocodile clips via the aluminum foil. The current then enters a circuit from 3V (plus pole), via the switch and back to P2.

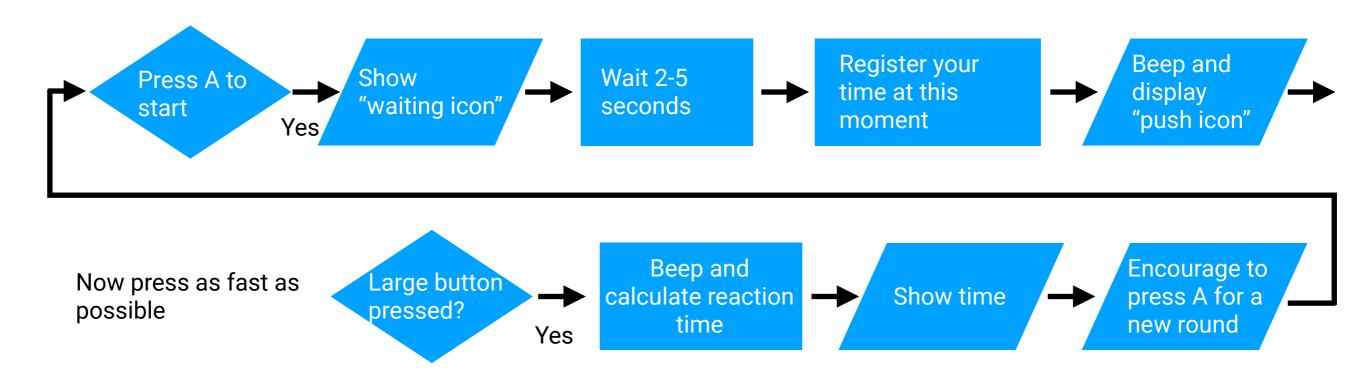
The current in P2 can be measured with digital read P2, and will give the answer 1 if a certain amount of current passes through, and 0 if no current passes through the circuit.

Furthermore, we have coded so that we will make a beep in the speaker if there is current through the circuit. Then an electrical signal is sent out from P0, through the buzzer and back to GND (ground). We stop the beep with the block rest(ms).



#### Reaction time tester

This flow chart shows how the game should work. When we press A, we display an icon that symbolizes waiting before we press. Then we pause a random time between 2 and 5 seconds. As soon as the pause is over, we register the time from the micro:bit's internal clock, and display a new icon. Now the player must press as fast as possible. As soon as the button is pressed, we calculate the reaction time by looking at the difference between new time and old time.

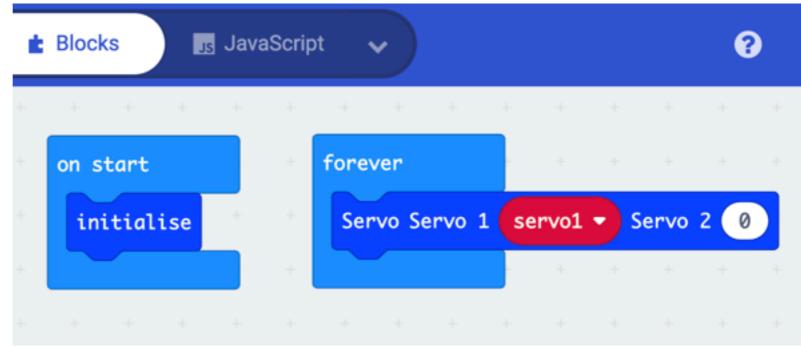


#### Code

Continue with your code that will contain this (delete other code)

Here is the code we start with:

Create the variables startTime and endTime



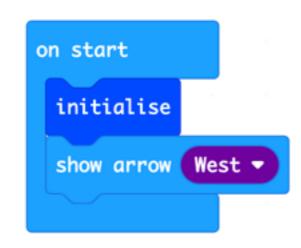


#### Code - At start

The first time the game starts, we want to encourage you to press A.

Enter a "show arrow west" on start.

Make sure that the wonderkit-block "initialize" is already inside.



#### Code - Button A

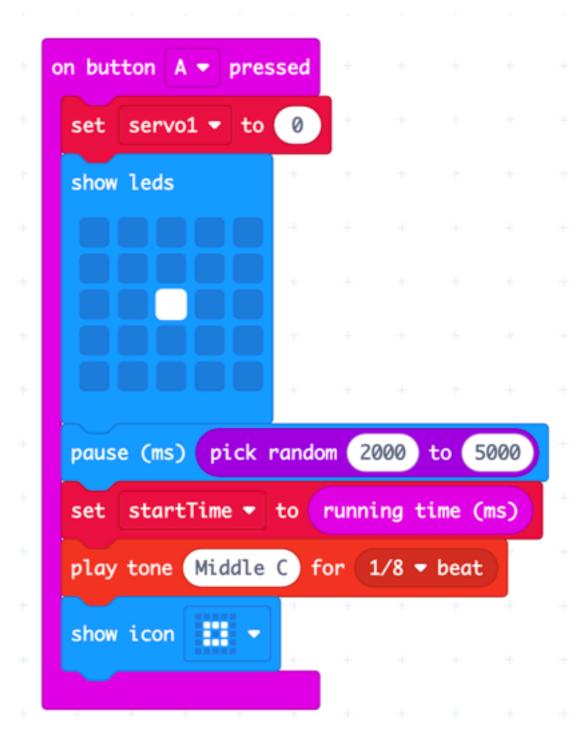
When we press A:

Display an icon that symbolizes pause. Feel free to create your own icon.

Pause at random between 2 and 5 seconds. (2000-5000 milliseconds)
Record what the internal clock is right now

Play a short note to make it clear that the timing has started

Show an icon that symbolizes timing



## Code - Record pressure and time

Repeat forever:

When we register current on P2:

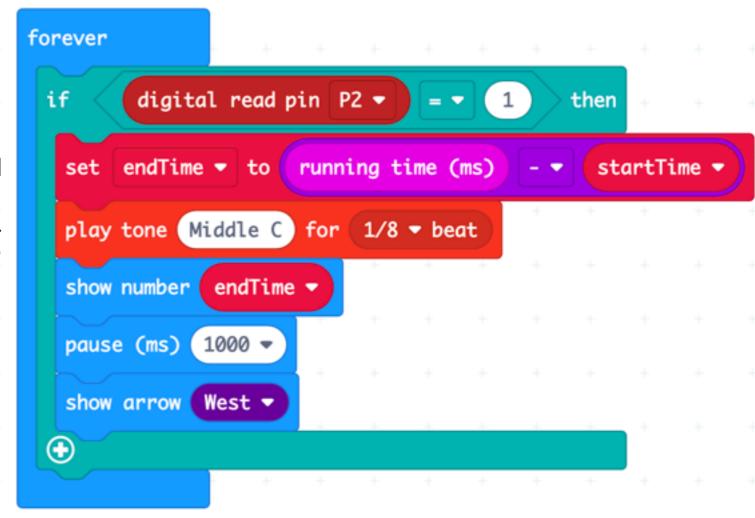
Calculate the end time by taking the current time minus the time when the testing started

Play a tone to say that pressure is registered. Feel free to choose a lighter tone (click white field to change)

Show the reaction time on the screen

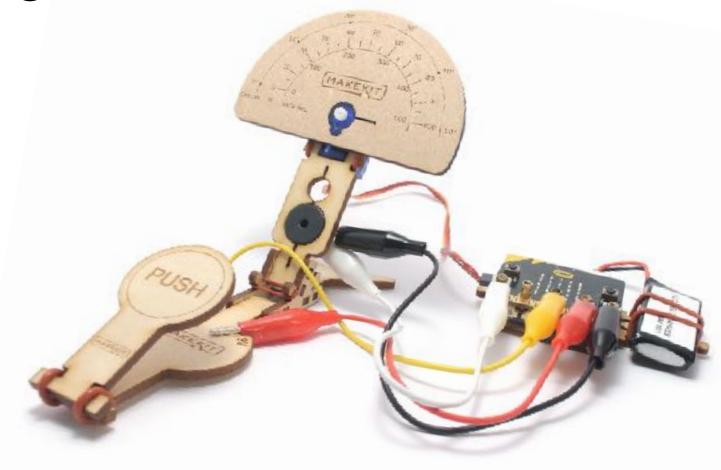
Take a break before a new game

Show arrow to the left, to indicate that you must press button A to start again.



Download the code to the Micro:bit

Test the game



Press A to start. When the beep comes, press the button as soon as you can. Then the time should be displayed on the screen. Who gets the lowest time?

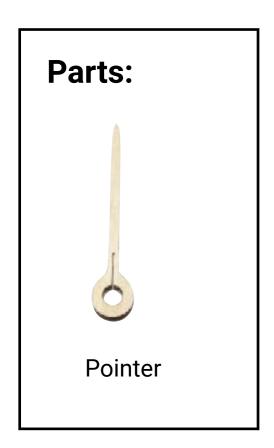
If that doesn't work, do the following:

Look carefully at your code. Are there any details you forgot?

Are the connections correct? Check that everything is connected correctly and that the gold-colored barrel nuts are tightened.

Does the micro:bit have power? It must be powered by USB or battery.

# Expand with "speedometer"



Add the following to the code: At start: set servo to 45 degrees (Center position)

Download the code to the Micro:bit



## Expand with "speedometer"

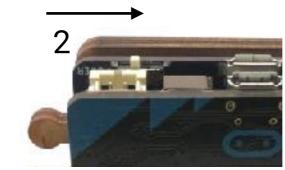
Plug in battery (1)

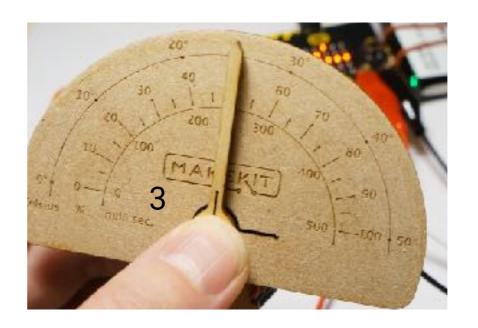
Turn on the power switch on the back of the control card (2)

Press the pointer in place (3)

FYI! Do not force the servo to change the angle. Just push the pointer straight in without rotating.







## Code - Display reaction time with servo

Top of on button A: Set servo1 to 0

Under play tone: Set servo1 to the following Map can be found under "math" (math blocks)

Download the code to the Micro:bit

```
on button
      servo1 ▼ to 0
 show leds
forever
         digital read pin P2 -
   play tone (Middle C) for 1/8 ▼ beat
                                    from low 125 high 375 to low
                          endTime ▼
   show number
                end⊤ime ▼
             1000 🕶
   pause (ms)
   show arrow West
  ①
```

## What happens?

When the code starts, the arrow is set to the middle position, because the angle in on start is set to 45.

When you press A, the arrow goes to the left, because the angle is set to 0.

When the time is measured, the arrow goes to the time in milliseconds that you have used.

The arrow shows an approximate reaction time between 125 and 375 milliseconds.







#### **Contact:**

Any questions, comments or feedback:

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Documents main folder: makekit.no/docs







